

First Results of Vegetation Height Retrieval from the 2016 UAVSAR AfriSAR Campaign

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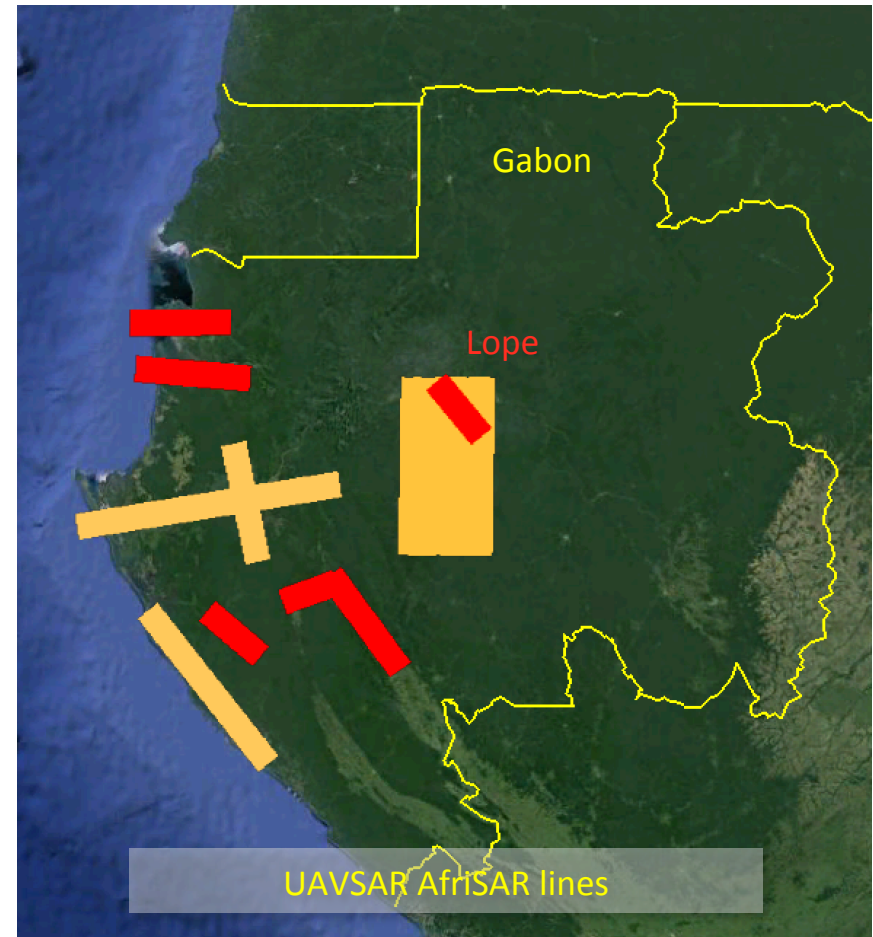
Jet Propulsion Laboratory, California Institute of Technology

Overview of the talk

- **Objective**
 - Show results of **tree height estimation** with AfriSAR campaign data and updated multi-baseline **UAVSAR PolInSAR** processor
- **Outline**
 - NASA/JPL contribution in the **AfriSAR campaign**
 - Revisited **multi-baseline PolInSAR UAVSAR** processor
 - Multi-baseline **selection algorithm** for tree height estimation
 - UAVSAR **PolInSAR vs. LVIS** lidar-derived tree height
 - Key messages

AfriSAR campaign and NASA/JPL contribution

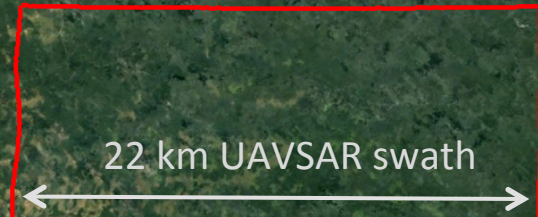
- Joint **NASA/ESA campaign** to support NISAR, GEDI and BIOMASS missions
- Cal/Val sites and algorithm demonstration
- NASA airborne data
 - **UAVSAR**: 39.6 flight hours, L-band polarimetric-tomographic data
 - **LVIS**: 32.4 flight hours
- L/P-band DLR and ONERA data
- 7 sites covered
 - Mabounie, Lope, Mondah, Rabi, Pongara, Ogooué, Mouila



- PolInSAR and TomoSAR (forest structure)
- PolSAR (biomass, wetland, cal/val)

NASA/JPL UAVSAR instrument

JPL UAVSAR
uavsar.jpl.nasa.gov



small variation
of UAVSAR inc. angle



ONERA
SETHI



DLR
F-SAR



	NASA/JPL UAVSAR	ONERA SETHI	DLR F-SAR
Looking	Left	Left	Right
Altitude	12.5 km	6.1 km	6.1 km
Swath width	22 km	5.8 km	6.6 km
Inc. angle	25°-65°	25°-55°	20°-50°
AfriSAR freq.	L	P / L	P / L
Bandwidth	80 MHz	50 / 150 MHz	50/100 Mhz
Resolution	1.66 x 0.6 m	3/0.8 x 0.8 m	3/1.5 x 0.8 m
Visit Gabon	Feb 2016	July 2015	Feb 2016

Lope site, optical image

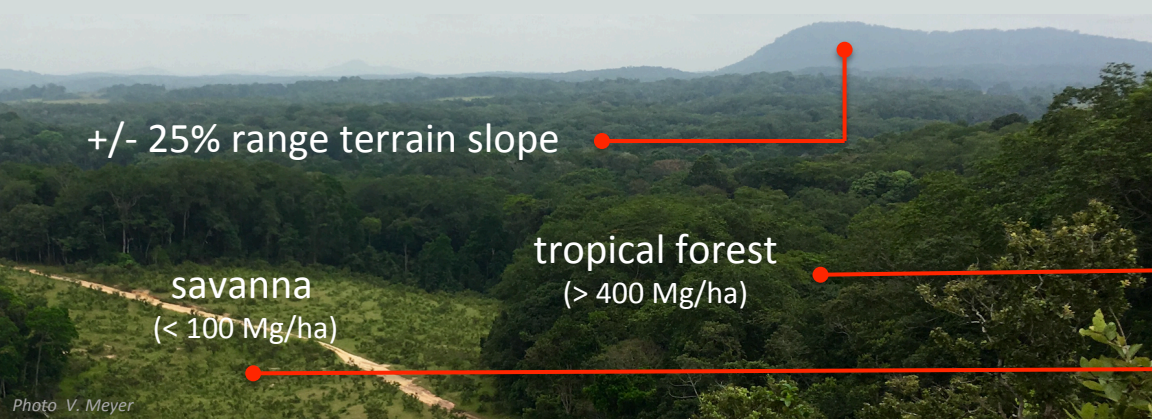
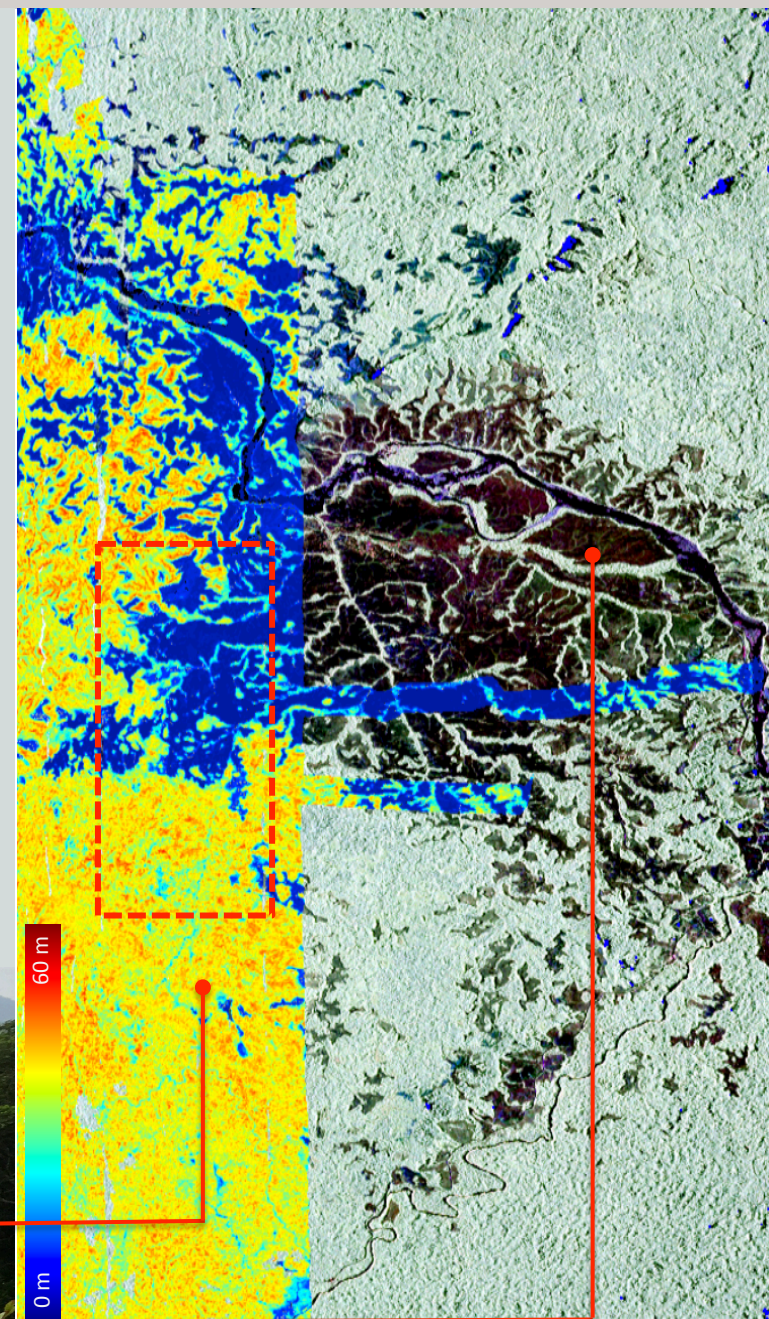
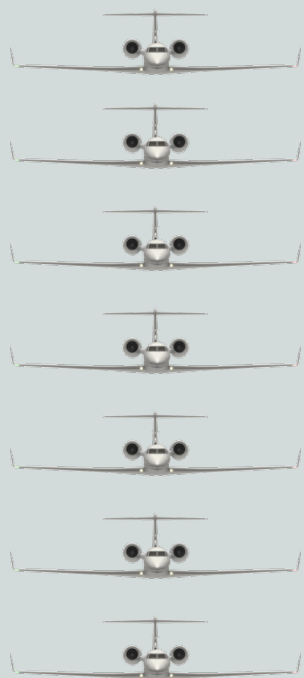
Lope site, data and study area

Stack #1 March 8

120 m	142 min	13:43
100 m	129 min	13:20
80 m	90 min	12:41
60 m	67 min	12:18
40 m	45 min	11:56
20 m	22 min	11:33
0 m	175 min	14:06

Stack #2 Feb 25

100 m
80 m
60 m
40 m
20 m
0 m



+/- 25% range terrain slope

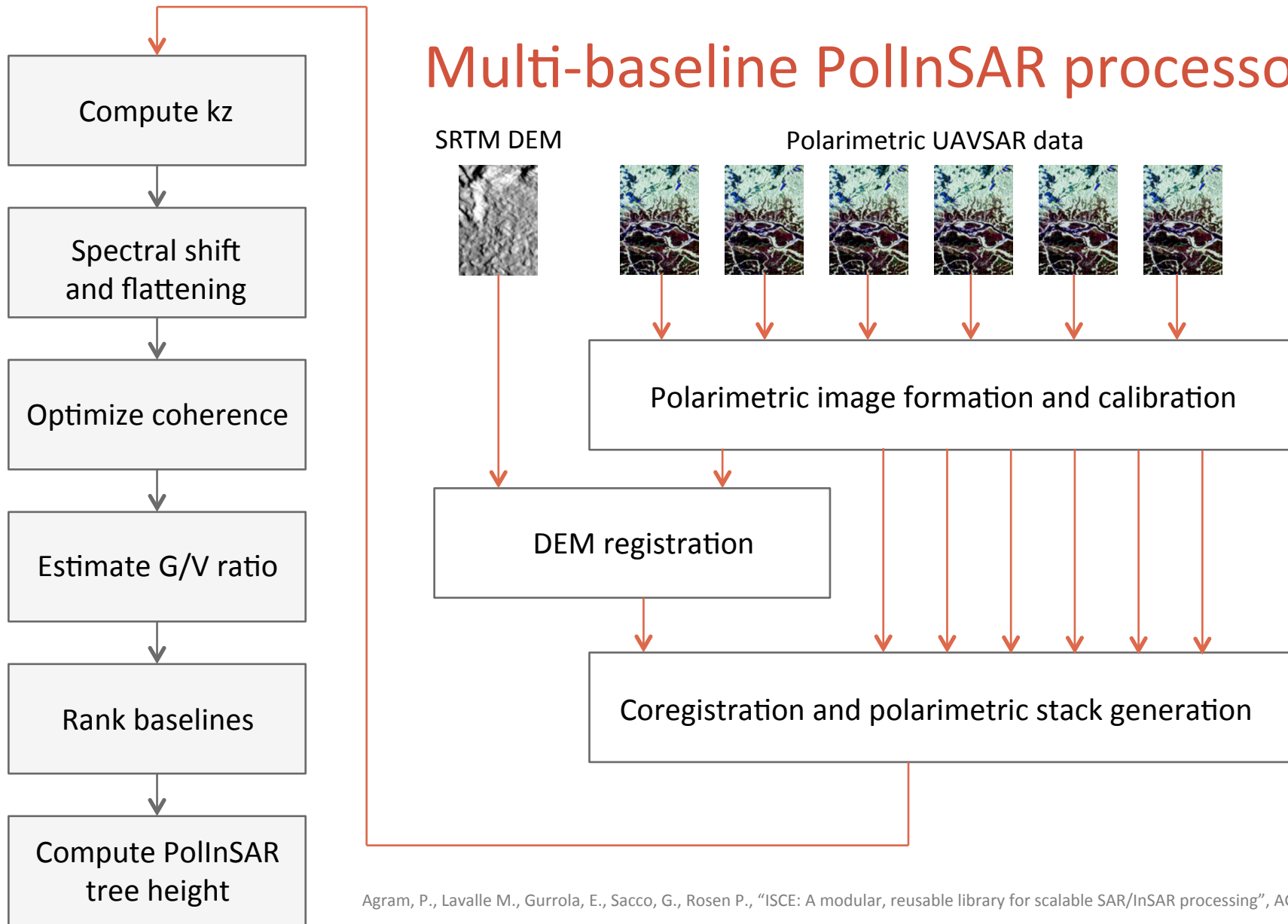
savanna
($< 100 \text{ Mg/ha}$)

tropical forest
($> 400 \text{ Mg/ha}$)

LVIS lidar RH90

UAVSAR PolSAR backscatter

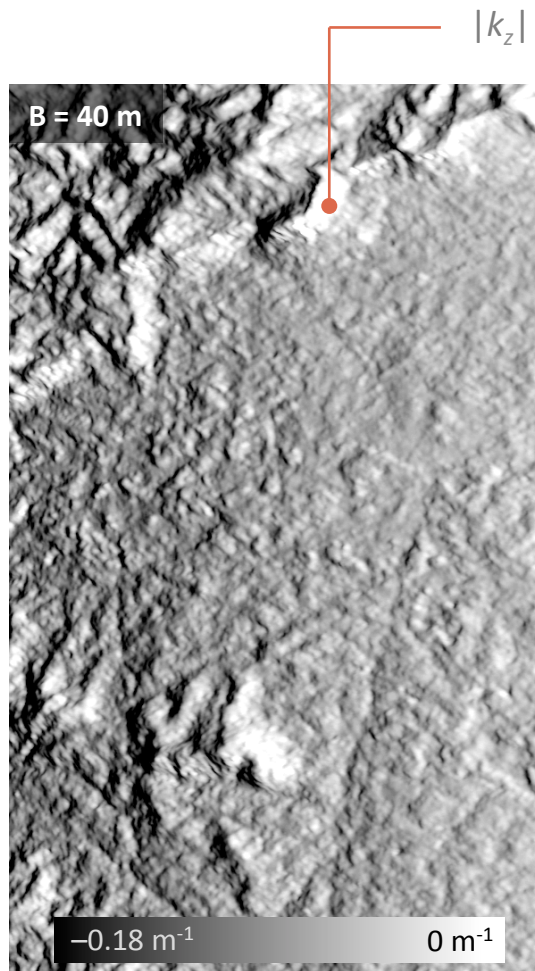
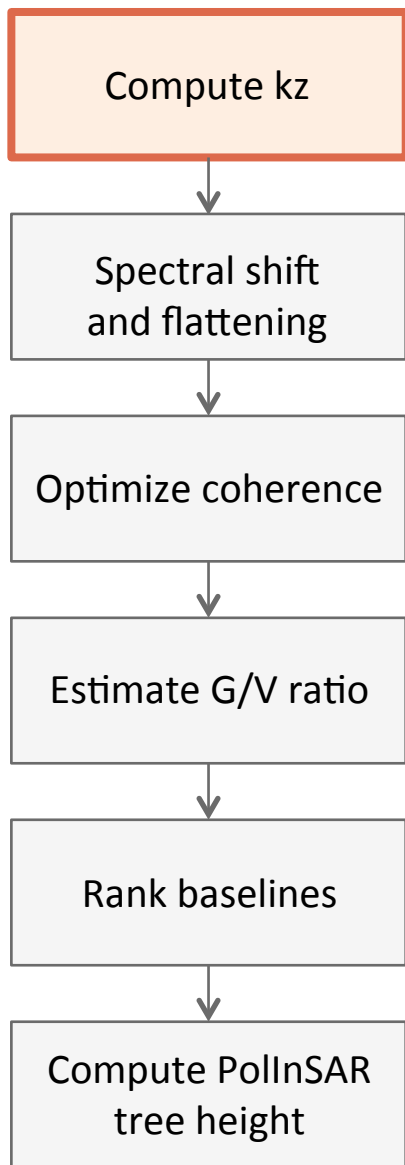
Multi-baseline PolInSAR processor



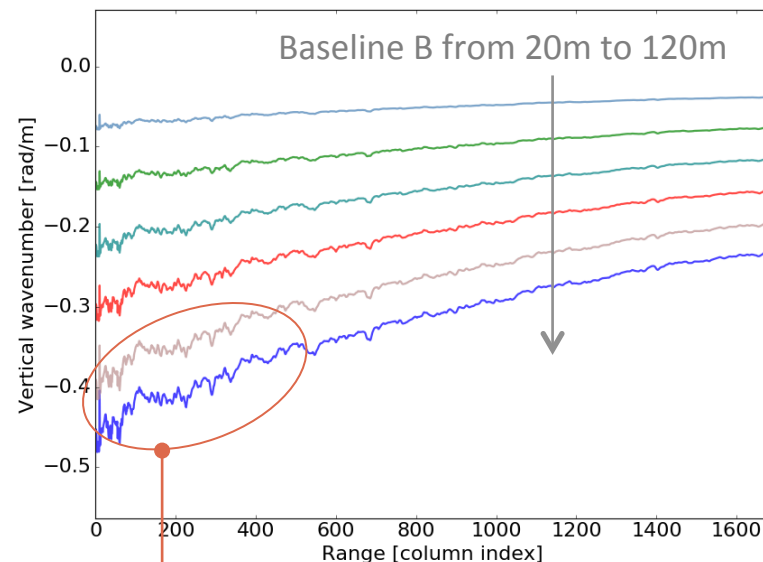
Agram, P., Lavalle M., Gurrola, E., Sacco, G., Rosen P., "ISCE: A modular, reusable library for scalable SAR/InSAR processing", AGU 2016.

Lavalle, M., Shiroma G.H.X., Agram P., Gurrola E., Sacco, G., and Rosen, P., "PLAnT: Polarimetric-Interferometric Lab and Analysis Tool for Ecosystems and Land-Cover/Land-Use Change Applications", in Proceedings of IGARSS 2016, Beijing, Jul. 2016.

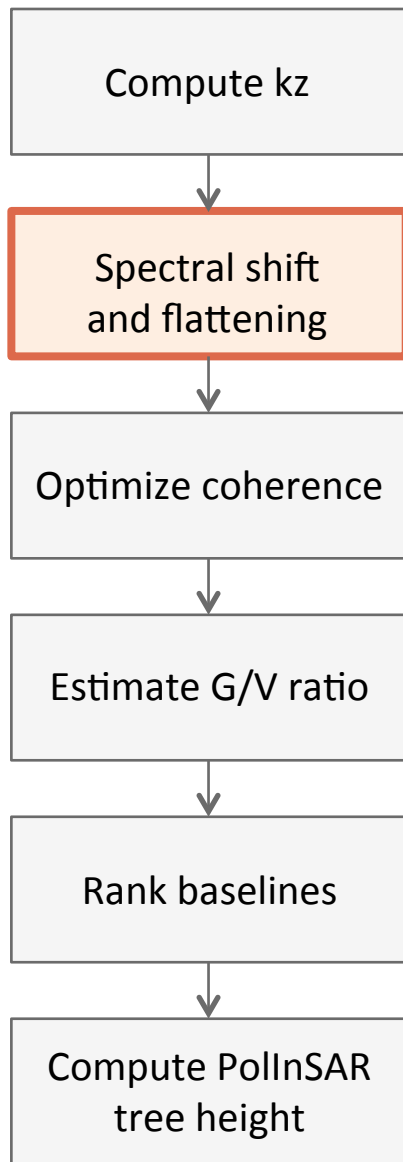
UAVSAR vertical wavenumber



- Calculated from **vector** geometry
- Derivative of look vector *wrt* vertical
- **Spectral-shift** and **DEM** included

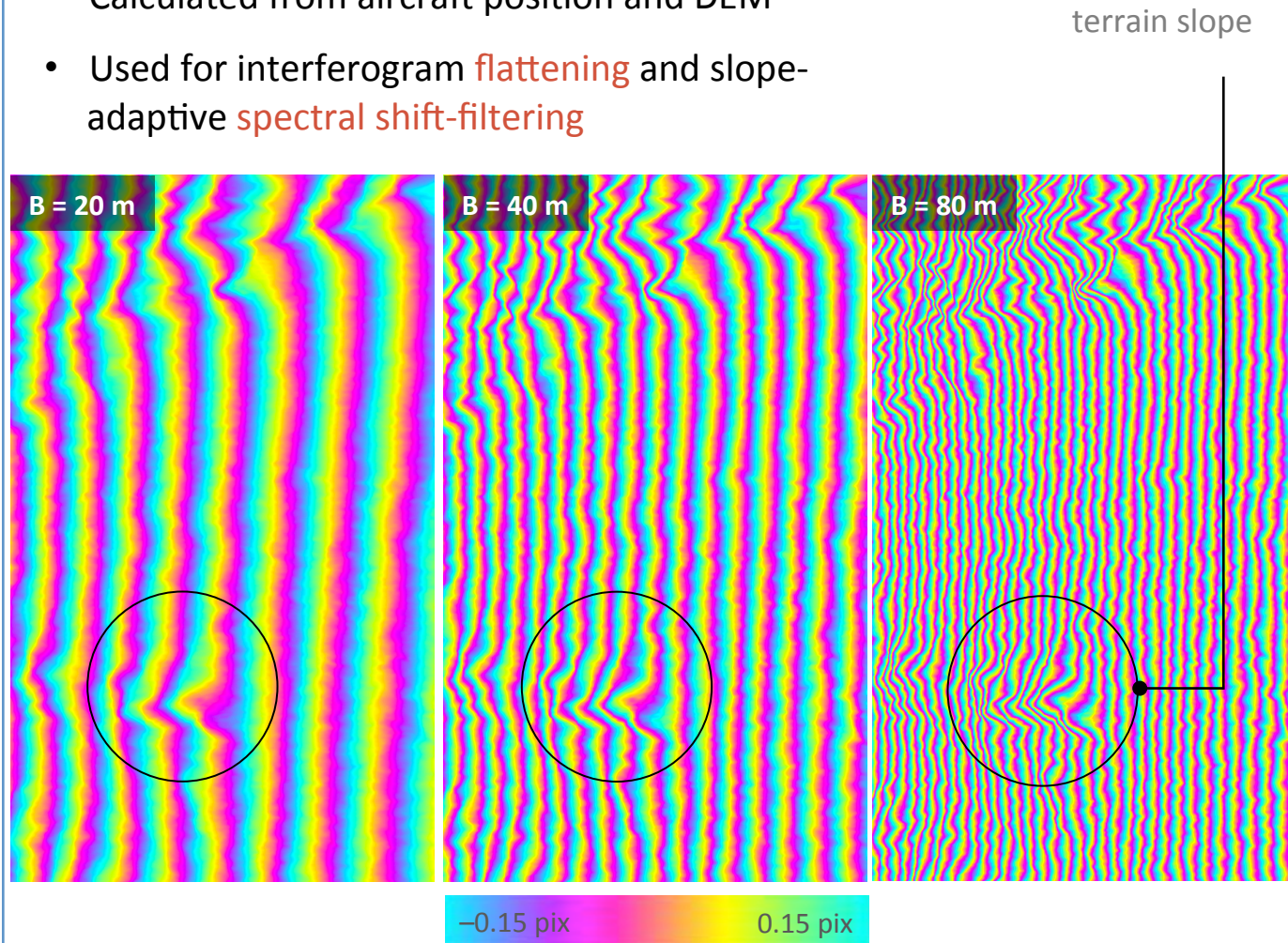


effect of terrain slope

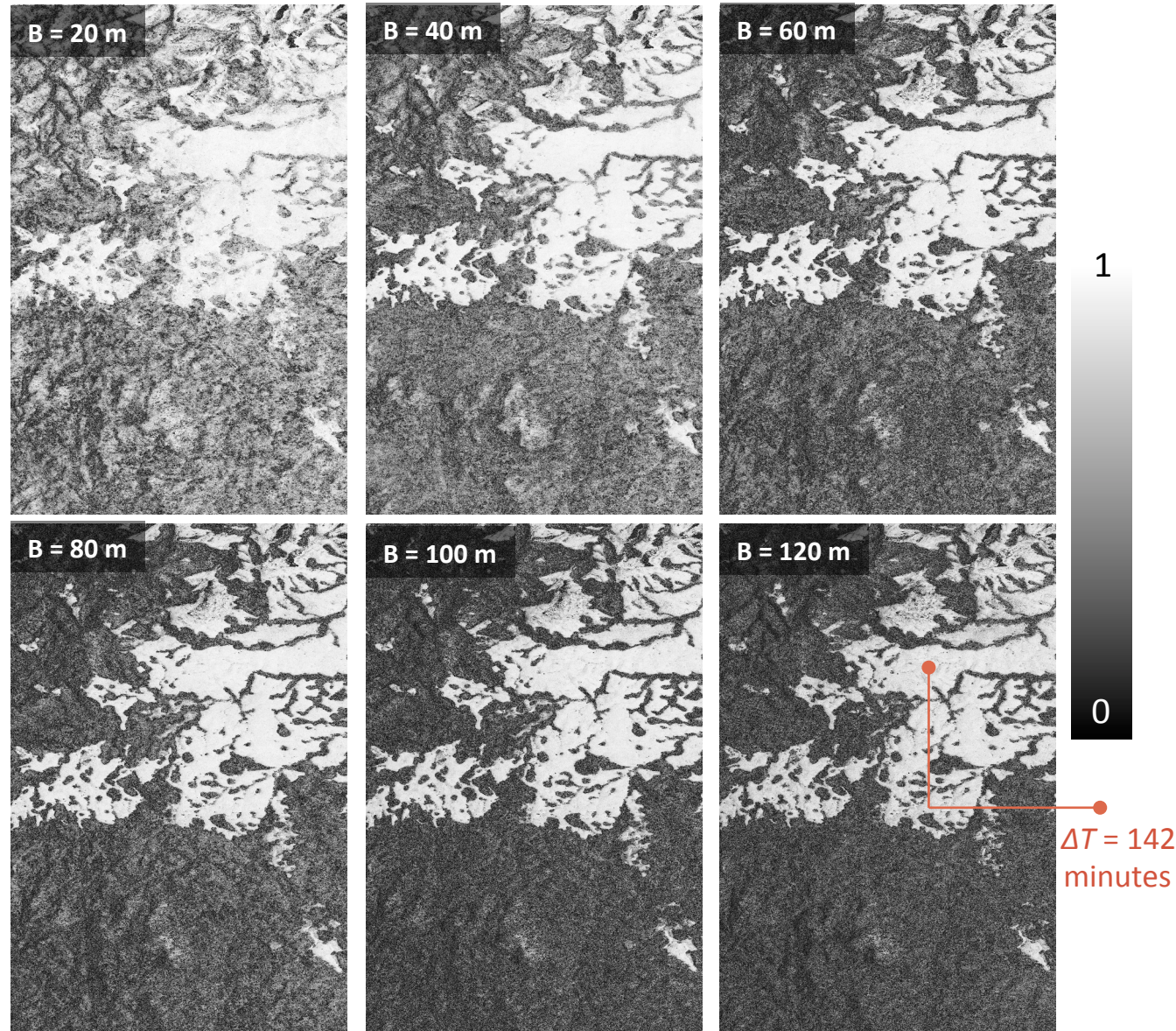
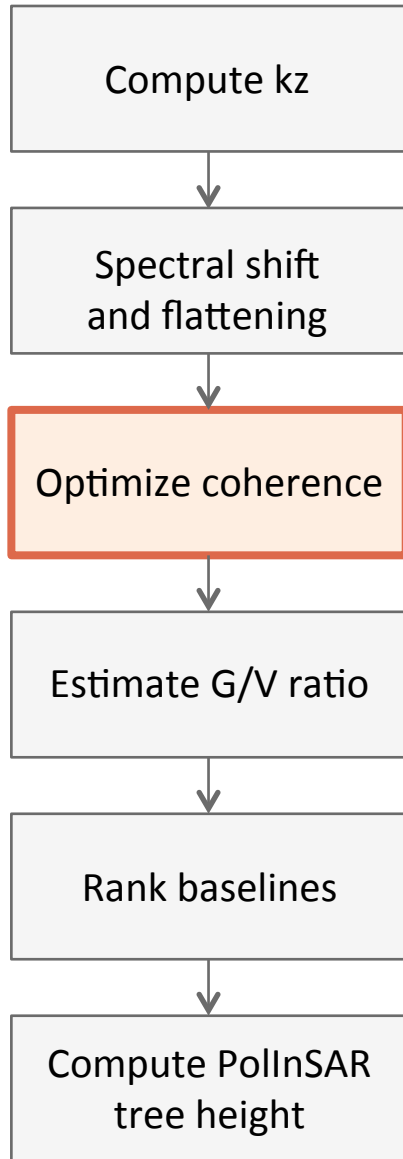


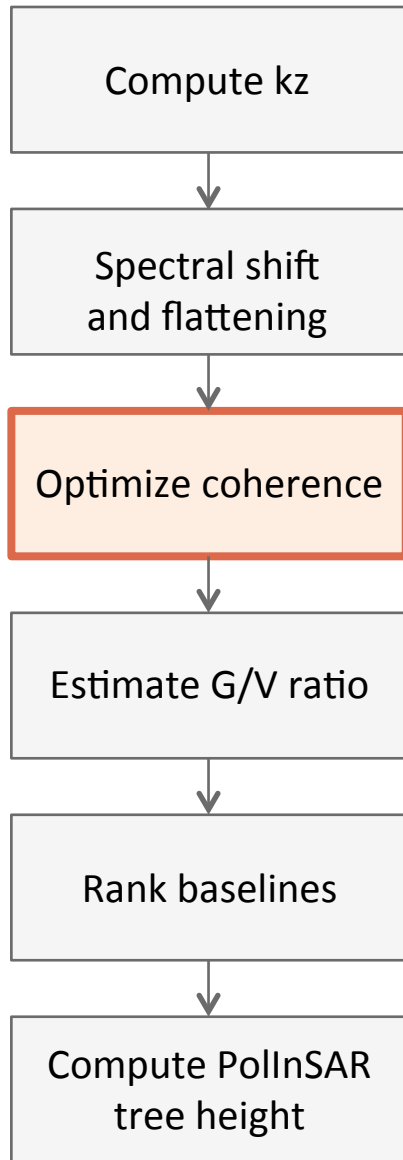
UAVSAR synthetic fringes

- Applied independently to **each pair**
- Calculated from aircraft position and DEM
- Used for interferogram **flattening** and slope-adaptive **spectral shift-filtering**

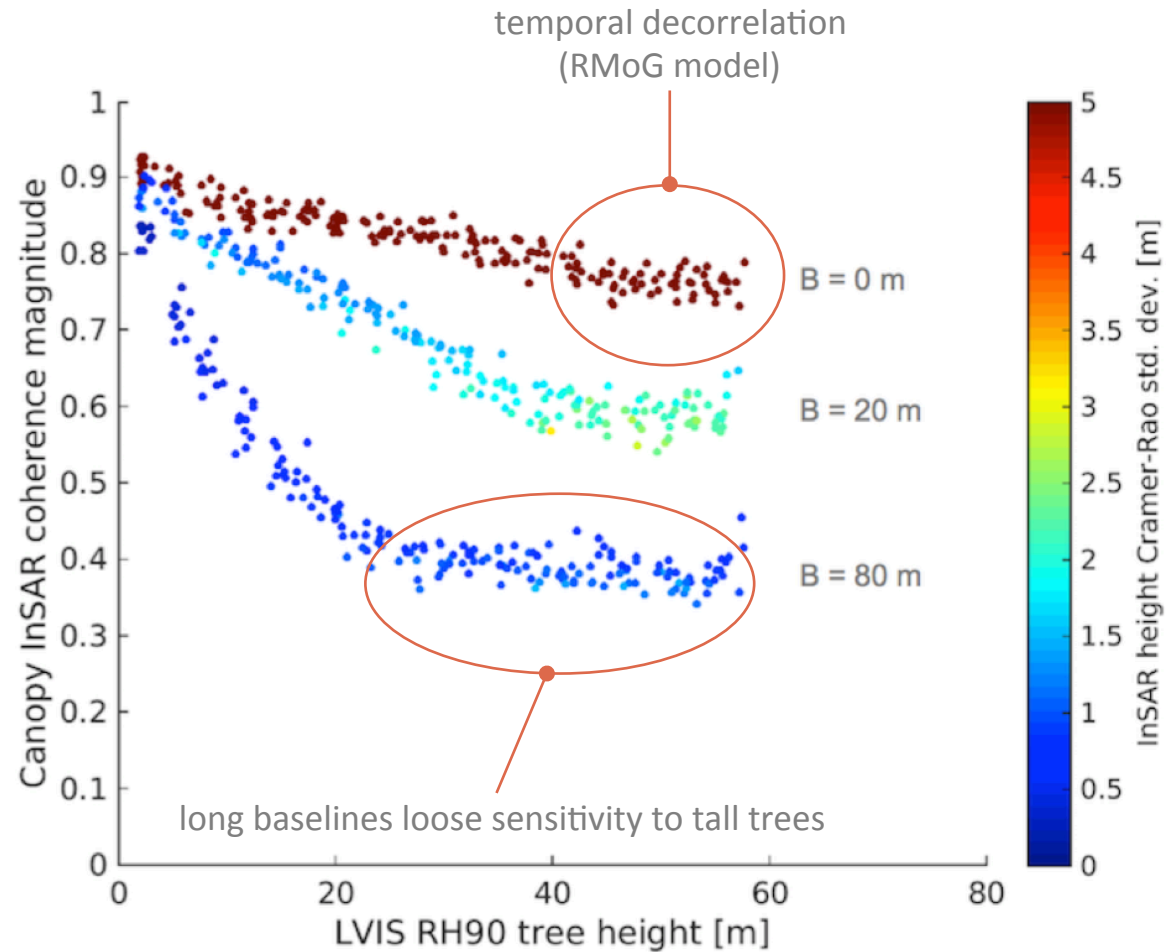


UAVSAR volume PolInSAR coherence

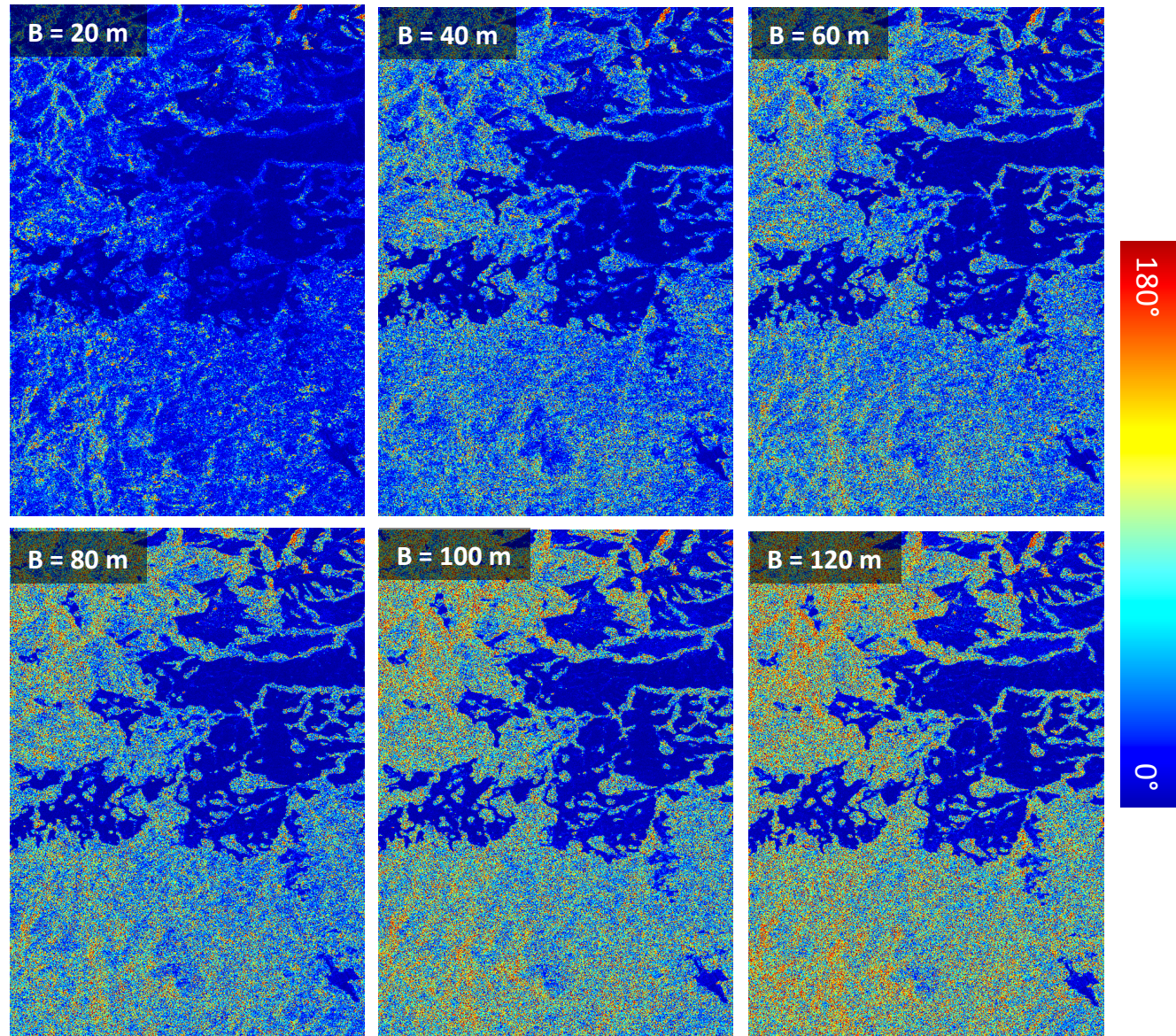
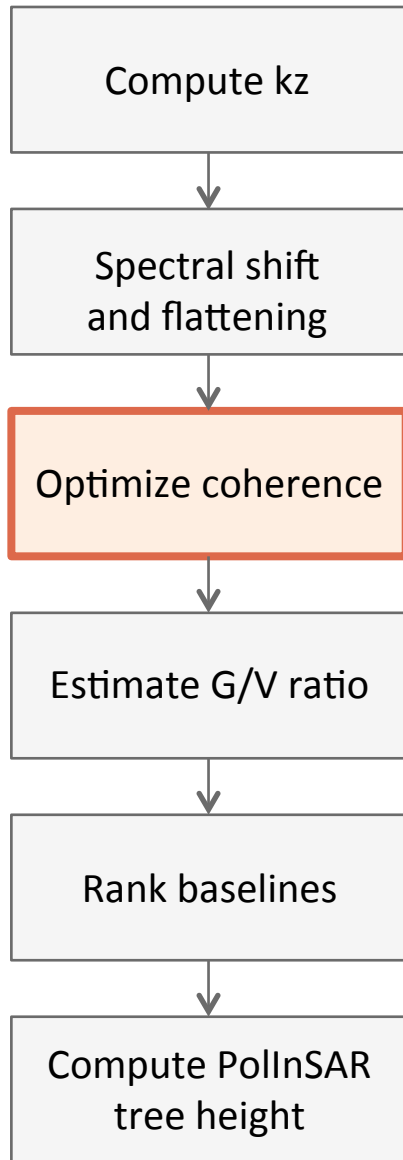




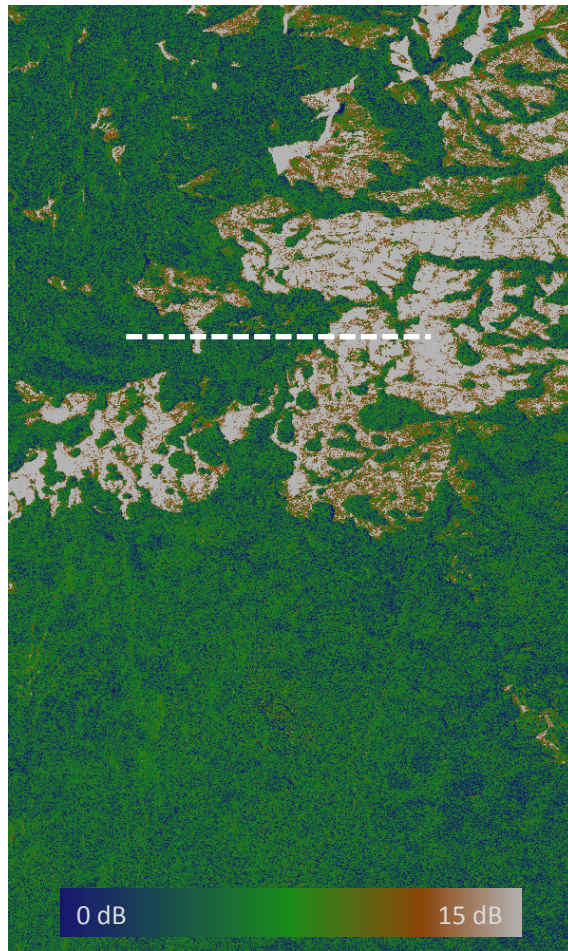
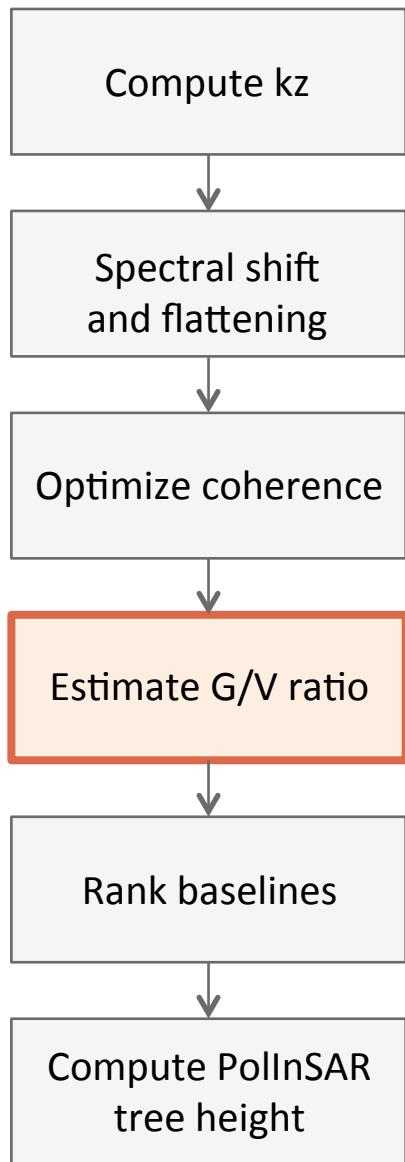
UAVSAR volume coherence vs. lidar height



Ground/Volume PolInSAR phase difference



Ground/Volume scattering ratio

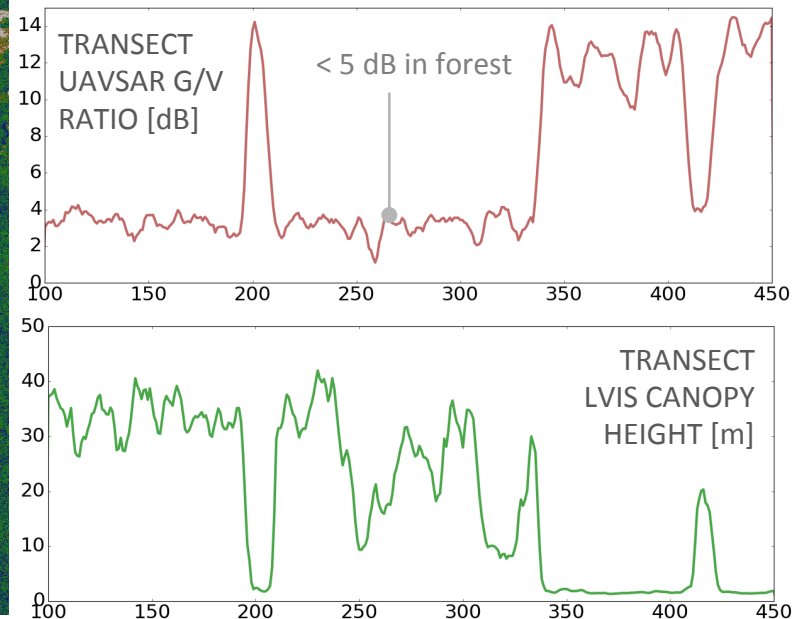


- Polarimetry only, no interferometry

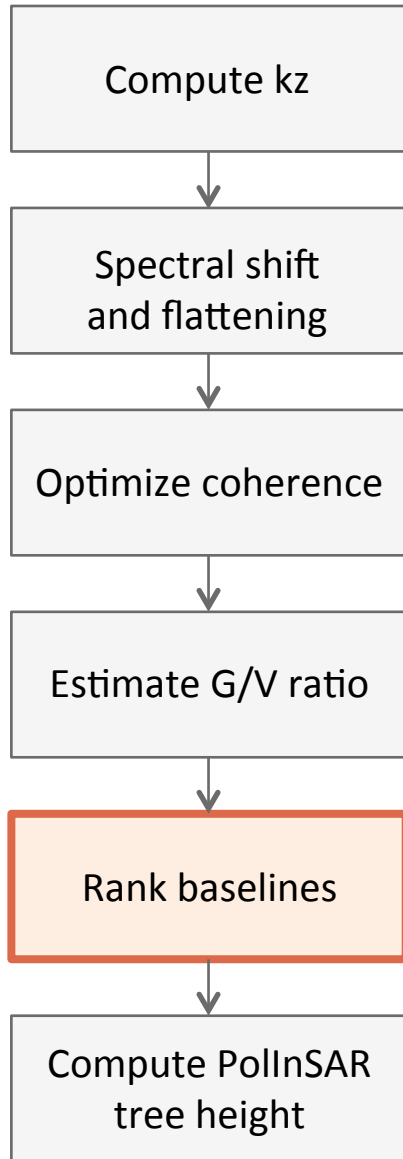
- Eigenvalue decomposition of ground/volume covariance matrix

$$[T_v]^{-1}[T_g]w = \lambda w$$

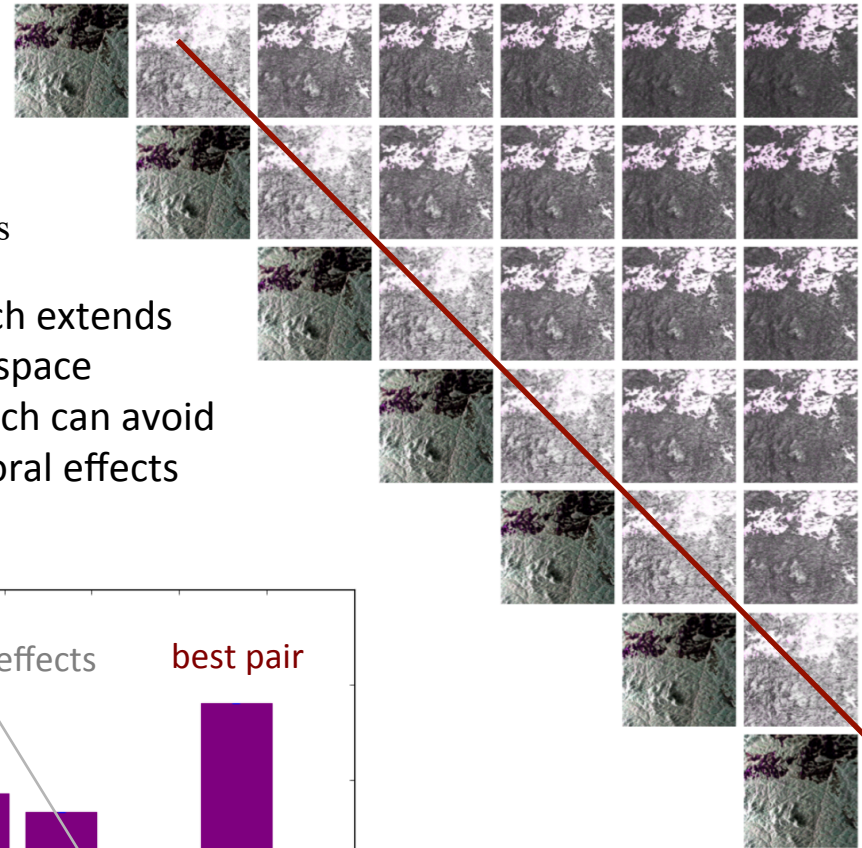
- Robust to terrain slope



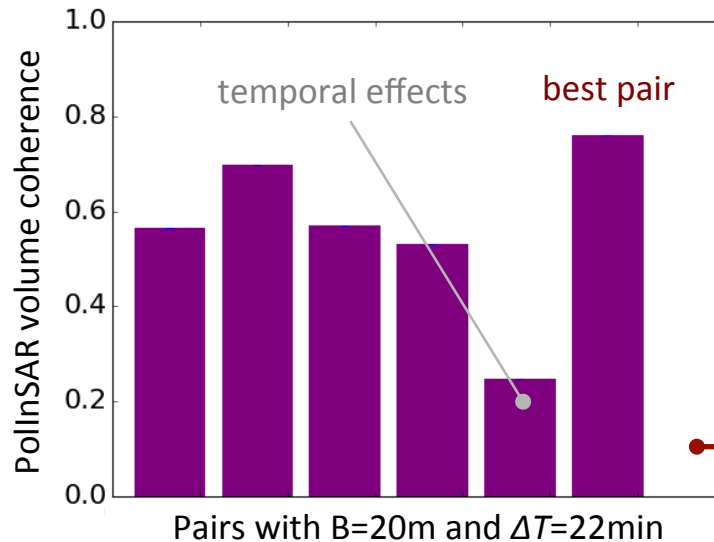
All-pairs vs. Best-pair approach



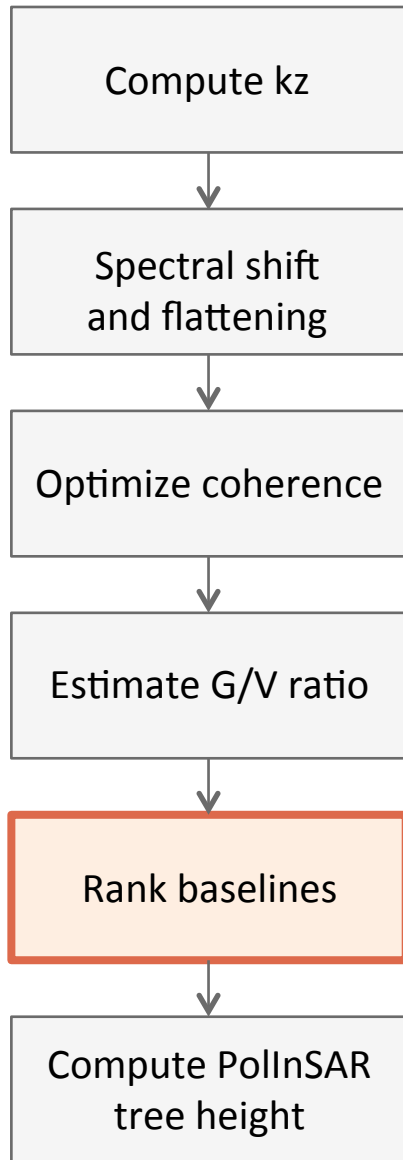
Polarimetric tomographic coherence stack



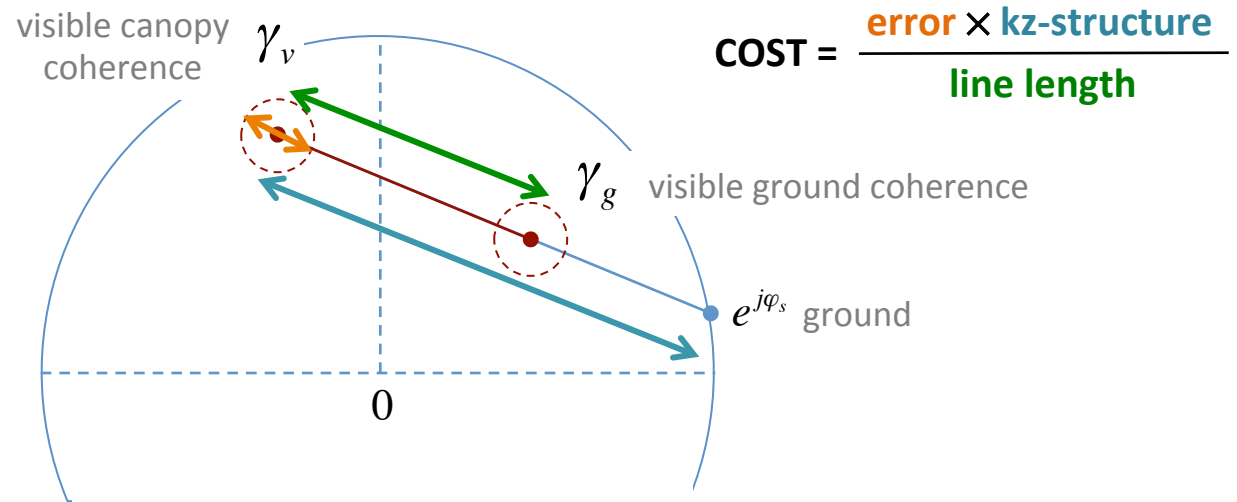
- $\frac{N(N-1)}{2} = 21$ pairs
- **All-pairs** approach extends the observation space
- **Best-pair** approach can avoid undesired temporal effects



Same baseline and interval, but different temporal decorrelation



Which UAVSAR baseline?



From literature

Error

Phase standard deviation divided by vertical wavenumber

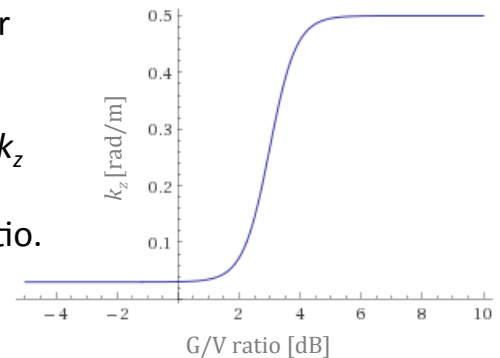
Line length

Volume/ground phase difference scaled by vertical wavenumber

We added

Kz-structure

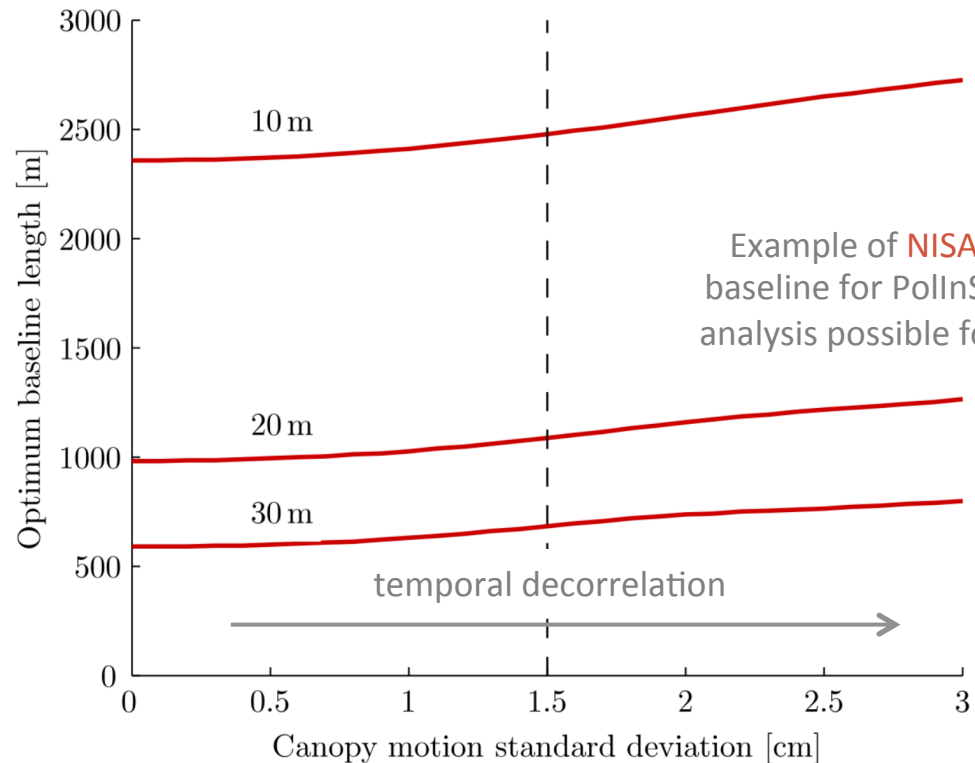
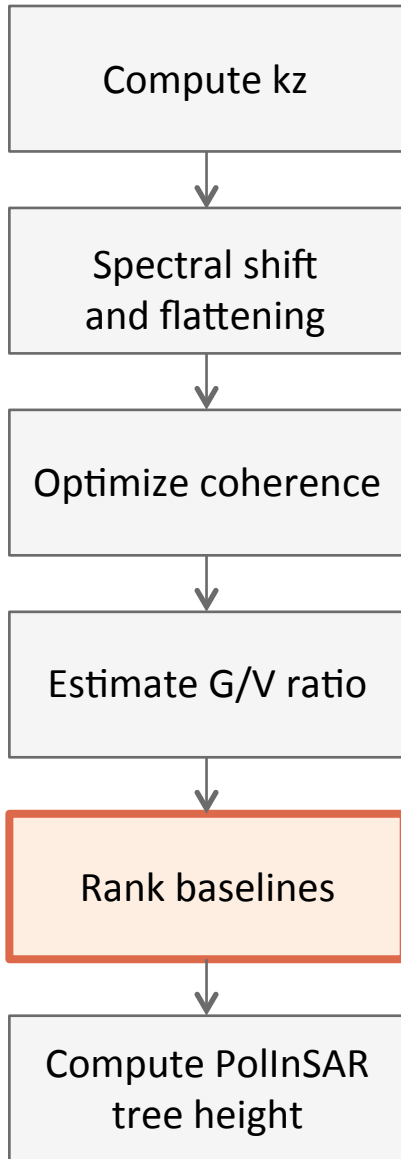
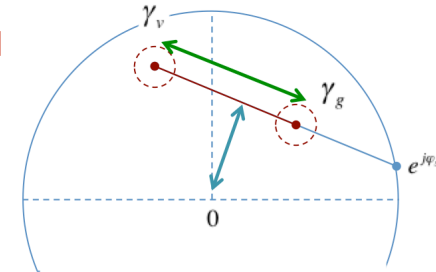
Departure of k_z from optimum k_z for a given forest structure.
E.g. Sigmoid function of G/V ratio. Depends on campaign design.



Cost function is robust against motion-induced temporal decorrelation

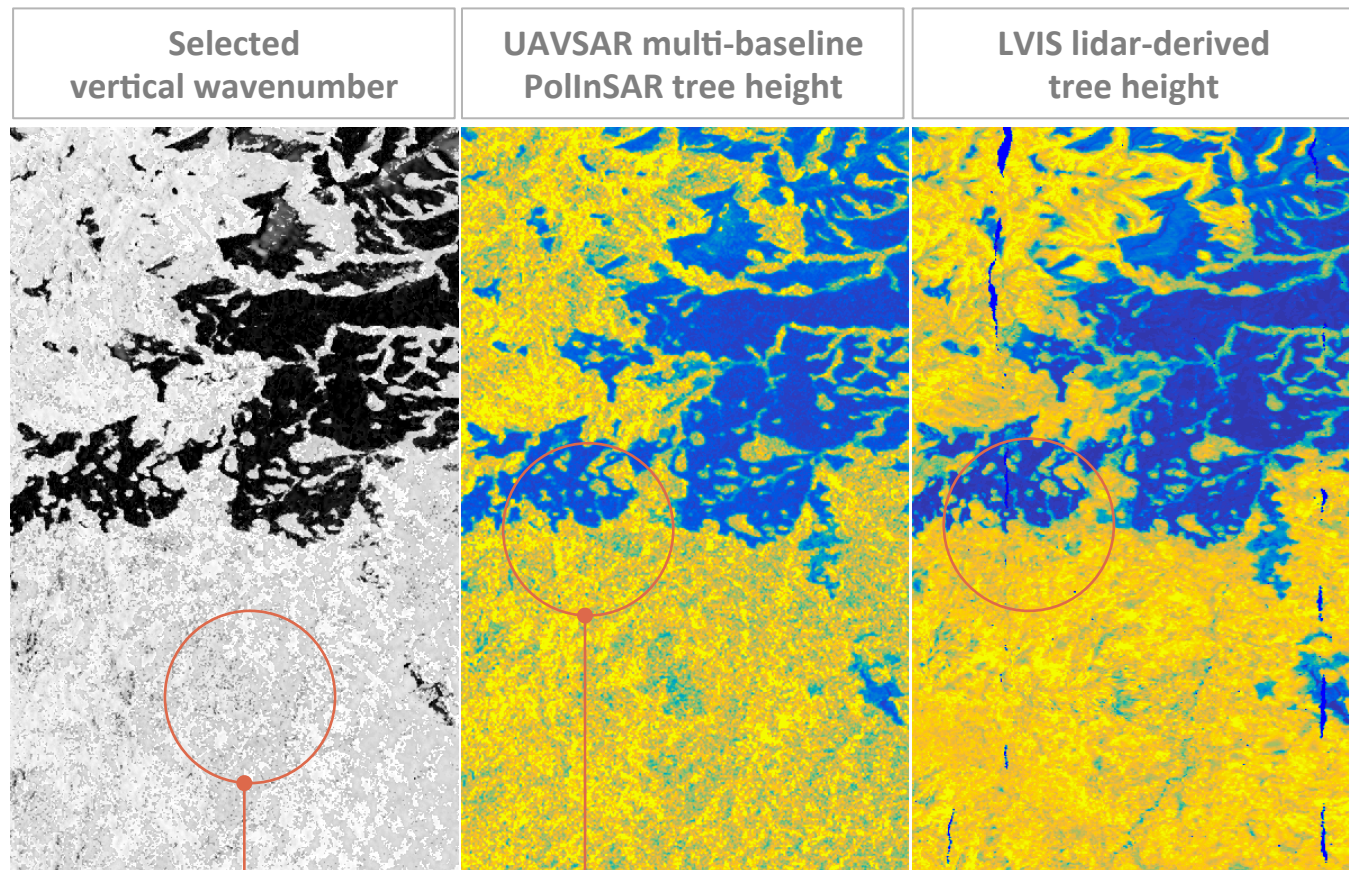
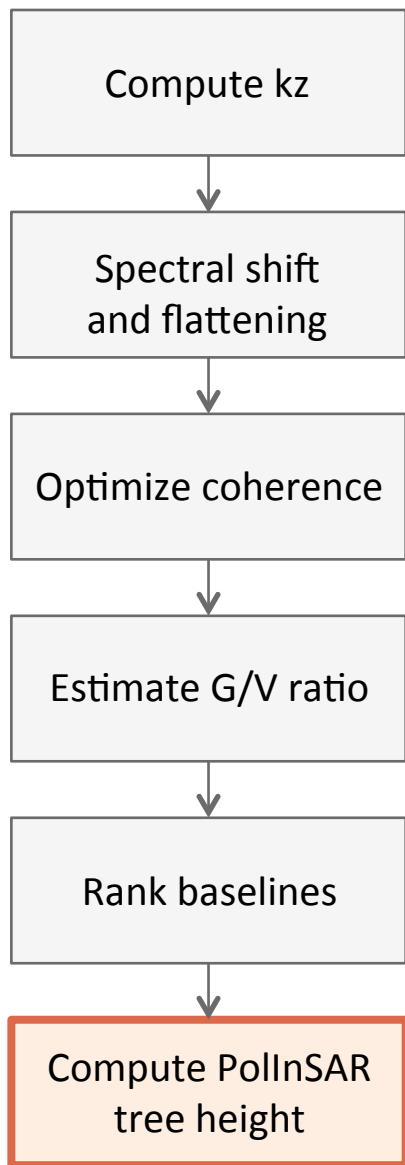
RMoG-model based temporal decorrelation **shrinks and tilts** the PolInSAR line, but cost function remains **stable**

$$\gamma = e^{j\varphi_g} \frac{\mu\gamma_{t_g} + \gamma_{vt}e^{-j\varphi_g}}{\mu + 1}$$



Example of **NISAR** optimal baseline for PolInSAR. Similar analysis possible for **BIOMASS**

Preliminary PolInSAR tree height



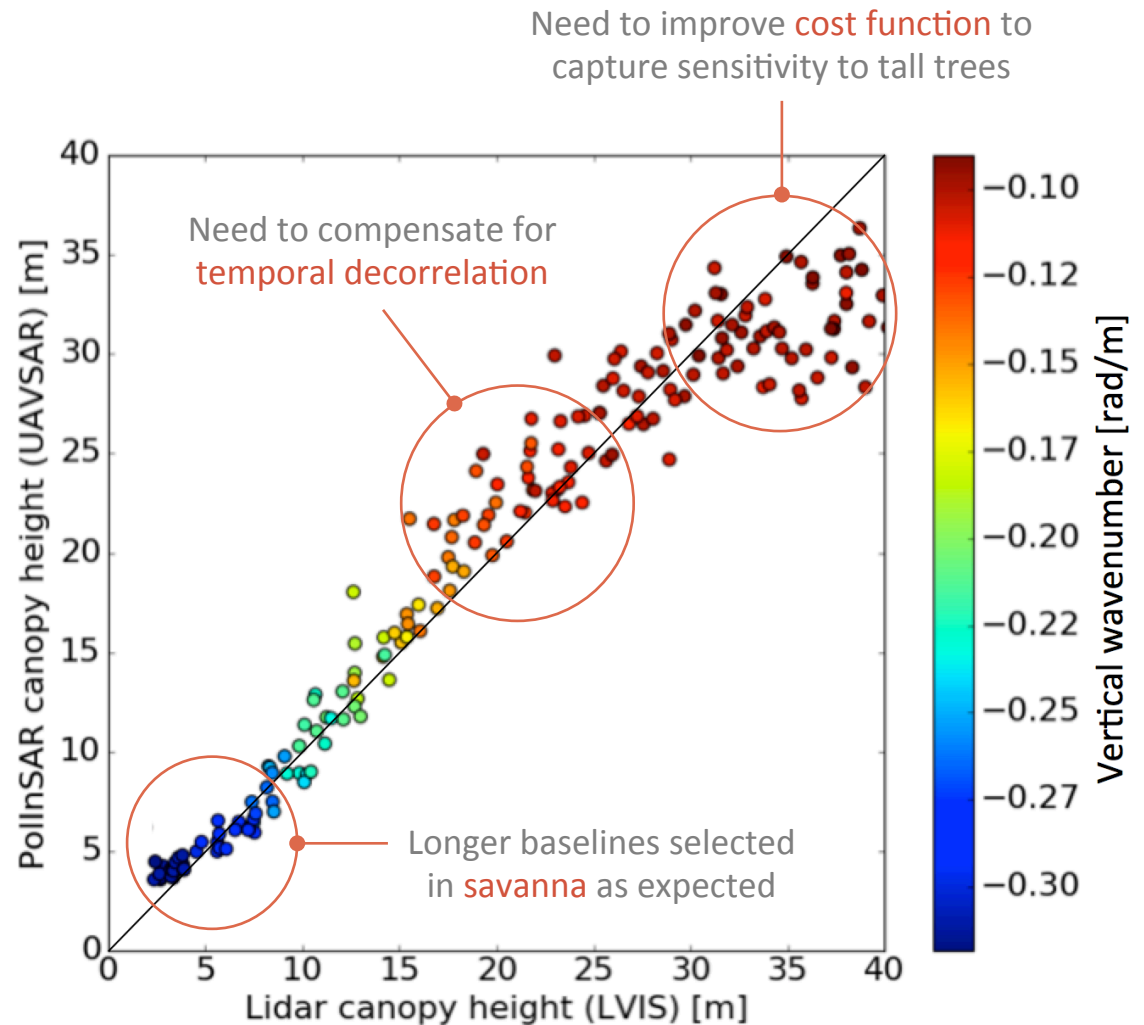
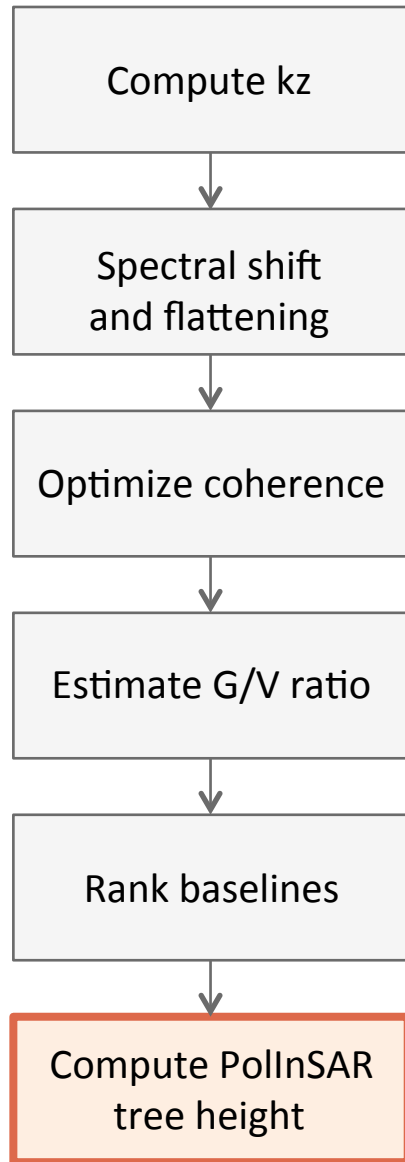
-0.32 m^{-1} -0.07 m^{-1}

0 m 50 m

terrain slope not visible

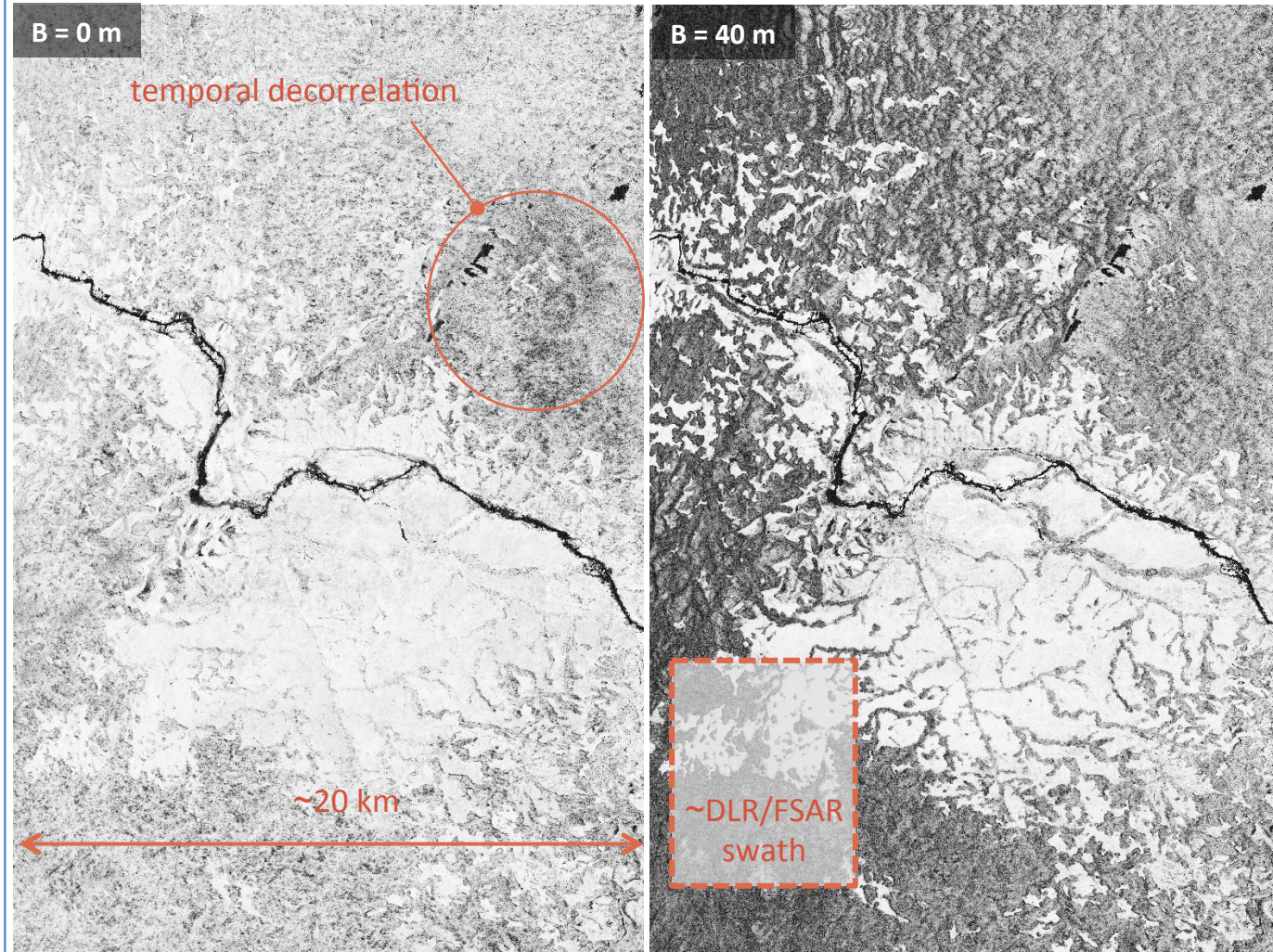
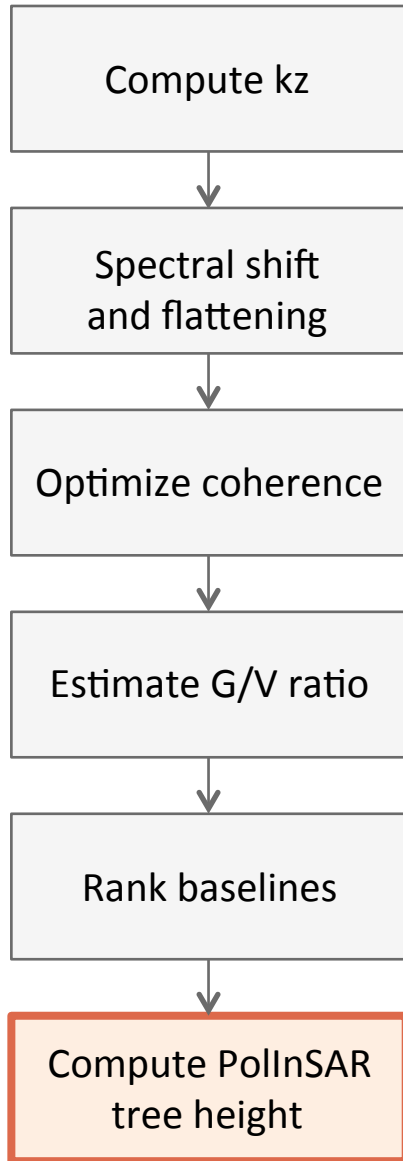
current estimation is better in savanna and savanna-forest transition compared with dense tropical forest

Preliminary PolInSAR tree height



Multi-baseline RVoG-model inversion. Quantitative assessment in progress.

UAVSAR Temporal-Volume coherence across the swath



Key messages

- Revised experimental, **multi-baseline UAVSAR** PolInSAR processor gives excellent coherence results
- **Baseline length** and **temporal decorrelation** are main drivers in PolInSAR tree height estimation
- **Best-pair approach** in multi-baseline PolInSAR helps maximize PolInSAR sensitivity to structure
- Cost function is robust to **temporal decorrelation**, but **compensation** for its effects is still needed
- Partial **ground visibility at L-band** in dense tropical forest is sufficient for PolInSAR height estimation
- **PolSAR and TomoSAR experiments** in progress (IGARSS 2017) → uavsar.jpl.nasa.gov
- Comparison and **inter-validation with ESA-funded** portion of AfriSAR campaign planned

