Cloud fraction determination for GOME-2 A/B with OCRA V3.0

Ronny Lutz, Sebastián Gimeno García, Diego Loyola and Fabian Romahn

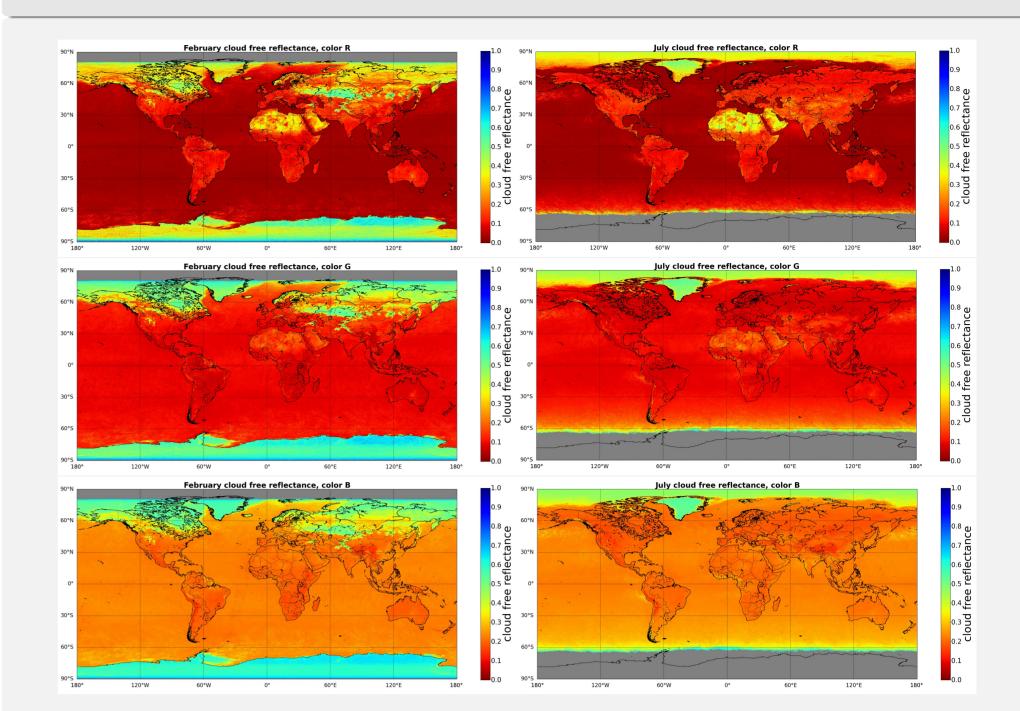
DLR — Remote Sensing Technology Institute, Oberpfaffenhofen, GERMANY

Introduction

- Precise cloud information is mandatory for accurate trace gas retrievals
- OCRA–ROCINN cloud retrieval algorithms operational for GOME-2 on Metop-A and -B and GOME on ERS-2
- OCRA: Optical Cloud Recognition Algorithm
- Cloud fraction (CF) retrieval using a RGB color space approach
- Main improvements in V3.0:
 - New corrections for PMD instrumental degradation
 - New corrections for scan-angle dependency and latitudinal dependencies
 - Improved sun-glint flagging and removal & retrieval over snow/ice
- **ROCINN: Retrieval Of Cloud Information through Neural Networks**
- Retrieval of cloud height (CH), cloud albedo (CA) and cloud optical thickness (COT)
- Two cloud models used in ROCINN V3.0:
 - CRB: Clouds as Reflecting Boundaries
 - CAL: Clouds As scattering Layers
- Main improvements (see talk of S. Gimeno Garcia on 10.06.)
 - New corrections for O₂ A-band instrumental degradation
 - New inversion scheme: Tikhonov regularization for CRB & CAL

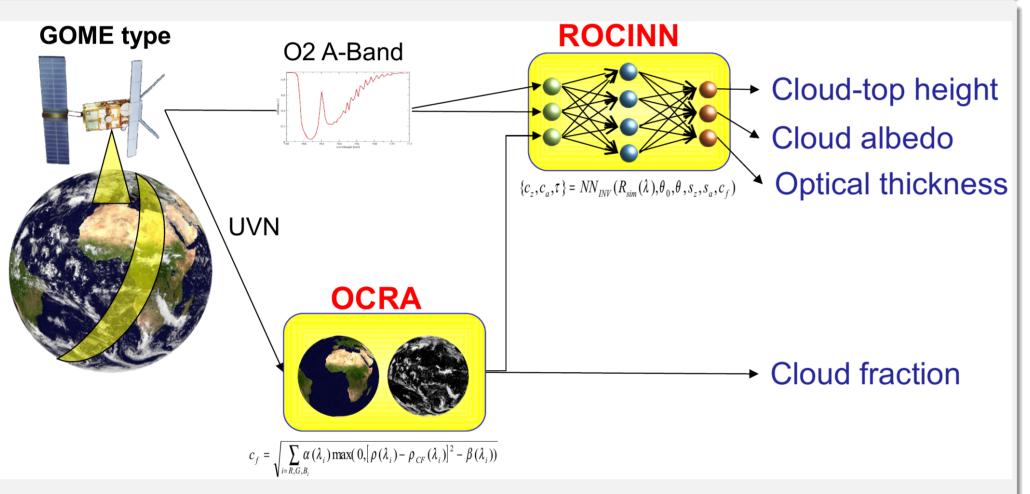
OCRA–ROCINN cloud retrieval algorithm

Cloud free background



 TOA cloud free reflectance background maps with 0.2 degree resolution for February and July for colors RGB: Red (569-804 nm), Green (400-557 nm), Blue (321-384 nm)

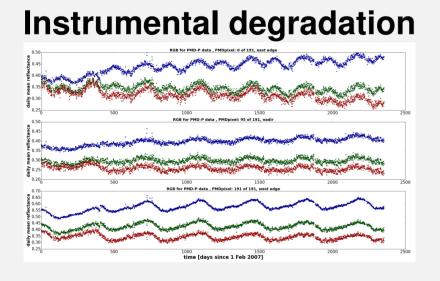
Normalized rg-color diagrams

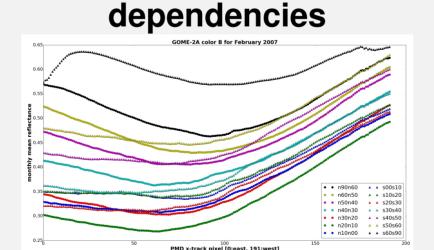


 OCRA divides a scene into a cloud free background and a contribution due to clouds

Reflectance corrections

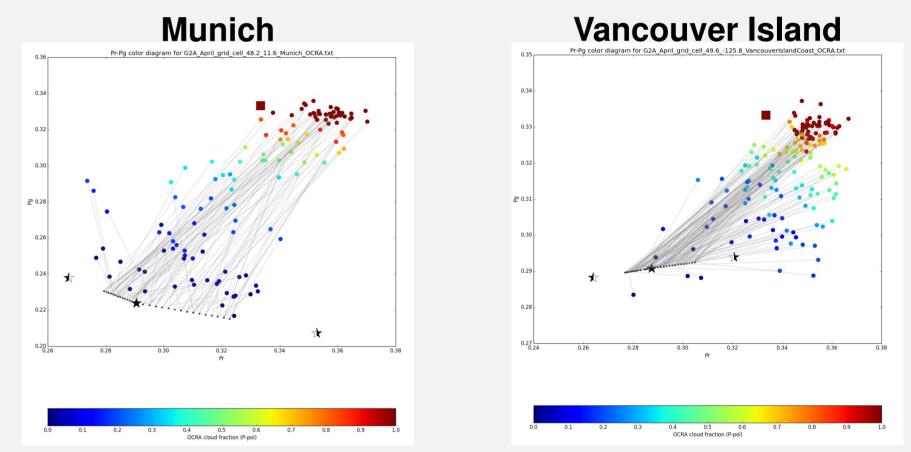
 Correction factors are calculated as function of time, λ-band, latitude and viewing zenith angle (VZA)





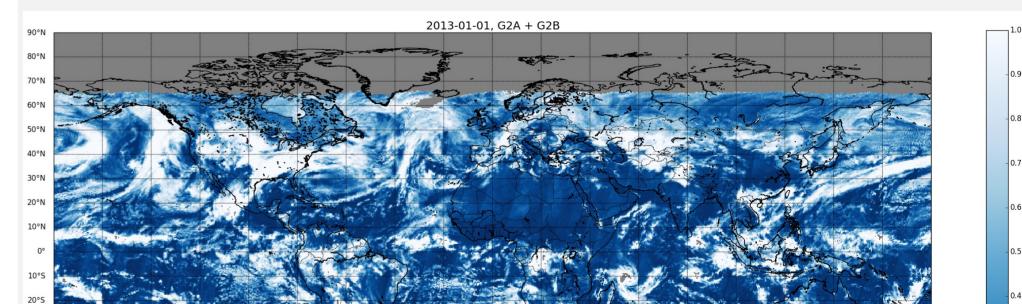
Scan angle and latitudinal

- Srd order polynomial for long term degradation (left)
- 4th order polynomial for scan angle and latitudinal dependencies for each month of the mission (right)



- GOME-2A PMD measurements from 2007 to 2013 for the month April for a 0.2 x 0.2 degree grid cell near Munich (left) and Vancouver Island (right)
- Each measurement (dot) is connected with its corresponding cloud free value (star) and color coded with its resulting OCRA cloud fraction. The red square marks the white-point at (1/3,1/3)

OCRA cloud fraction map (GOME-2 A/B)



OCRA cloud fraction

Inputs: measured reflectance and cloud free reflectance

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$$f_{c} = \sqrt{\sum_{i=R,G,B} \alpha(\lambda_{i}) \cdot \max\left\{0, \left\{\rho(\lambda_{i}) - \rho_{free}(\lambda_{i}) - \beta(\lambda_{i})\right\}\right\}}$$

- measured reflectance $\rho = \frac{\pi \cdot I}{I_0 \cdot \cos \Theta_0}$
- cloud free reflectance \(\rho_{free}\) from cloud free maps (see top right panel, maps available for each month of the year)
- ► scaling factor $\alpha(\lambda_i) = \frac{1}{(\rho(\lambda_i) \rho_{free}(\lambda_i))_{0.99}^2}$ via histogram analysis
- offset $\beta(\lambda_i) = (\rho(\lambda_i) \rho_{free}(\lambda_i))_{mode}$ via histogram analysis

20°5 30°5 50°5

Summary

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- OCRA uses a RGB color space approach, which can easily be adapted to other sensors. Cloud free maps and CF have also been calculated for the Ozone Monitoring Instrument (OMI)
- OCRA will be used for the operational TROPOspheric Monitoring Instrument (TROPOMI) cloud fraction.

