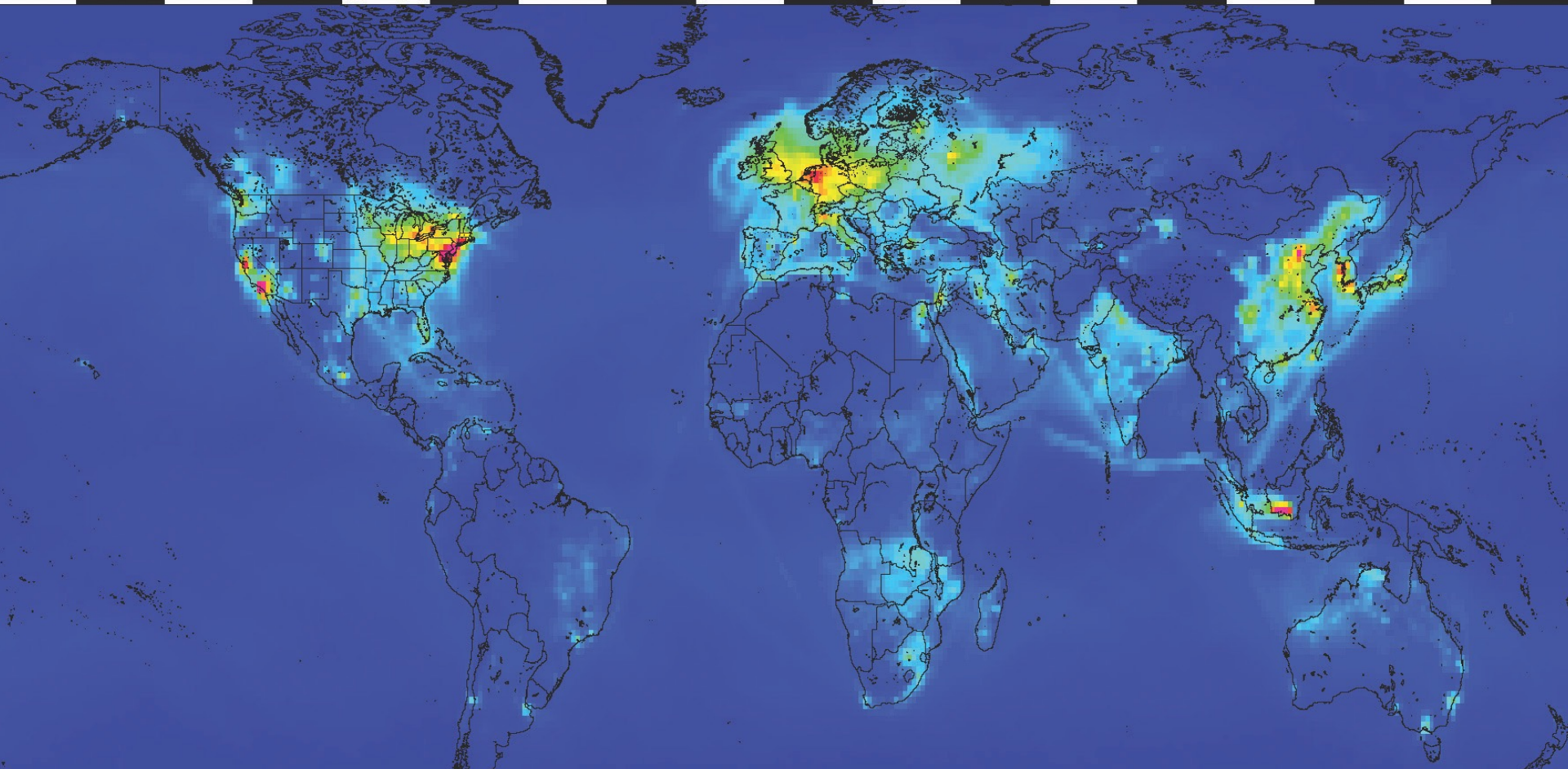


# Developments in the retrieval of NO<sub>2</sub> from OMI and TROPOMI observations



Royal Netherlands  
Meteorological Institute  
Ministry of Infrastructure and the  
Environment

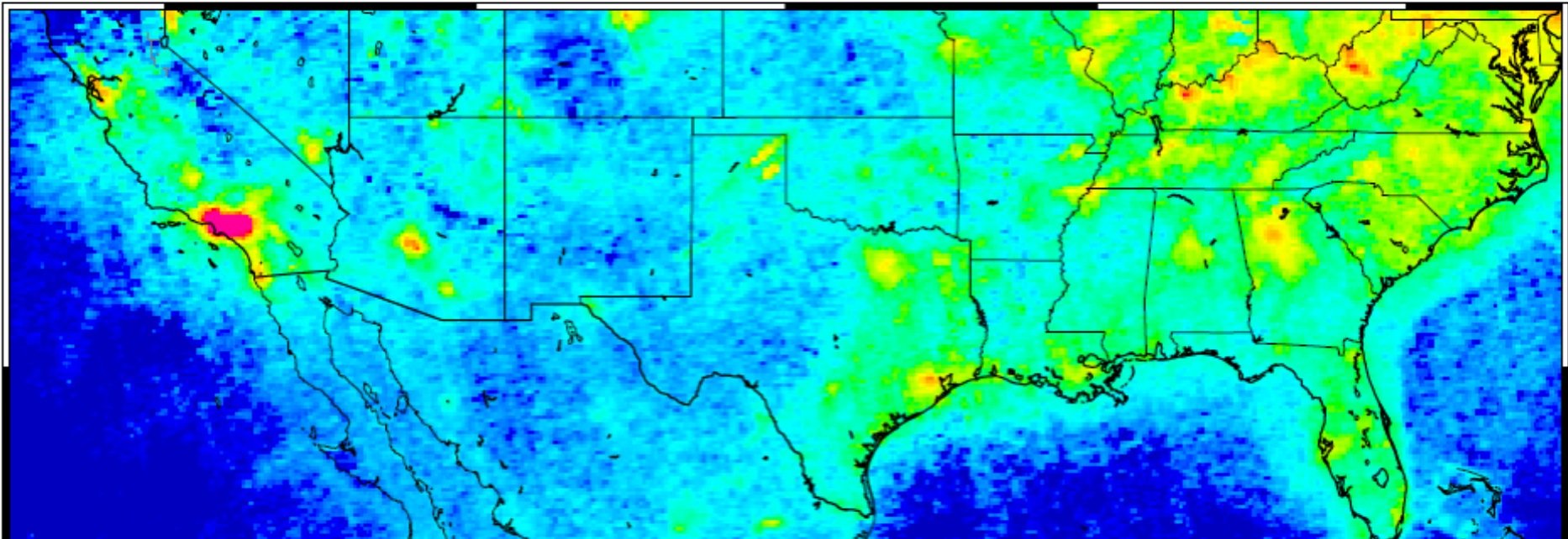
*Folkert Boersma, Jos van Geffen, Bram Maasackers,  
**Henk Eskes**, Jason Williams, and Pepijn Veefkind*



# OMI success-factors

OMI NO<sub>2</sub> provides a different perspective than GOME-2, SCIAMACHY

- Smaller pixels: **More spatial detail, less cloud interf.**
- Afternoon overpass time: **Sensitive to natural sources + chem.**
- Global coverage: **Massive data availability**
- Endurance: **Operational for 10 years!**
- Relative stability: **Good for trend analysis, data ass, etc.**



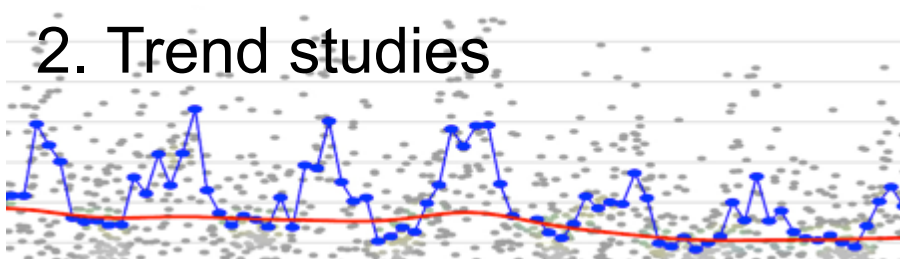


# Success of OMI NO<sub>2</sub> - many applications

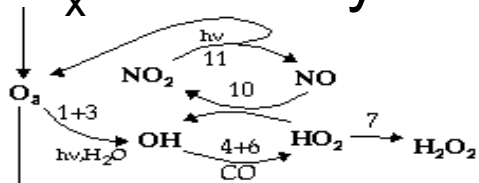
1. NO<sub>x</sub> emission estimates



2. Trend studies



3. NO<sub>x</sub> chemistry



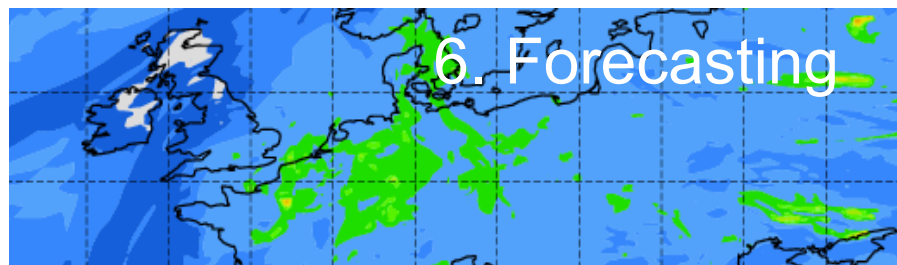
4. Chemical regimes



5. Surface pollution



6. Forecasting



7. Deposition



Scientist proposes shared delta satellite to monitor air quality

8. Outreach

Cheung Chi-fai

Hong Kong and Guangdong could launch a satellite of their own to monitor air quality and make pollu-

fine particles proposed by the government set the 24-hour average at about 75mcg of particles per cubic metre of air.

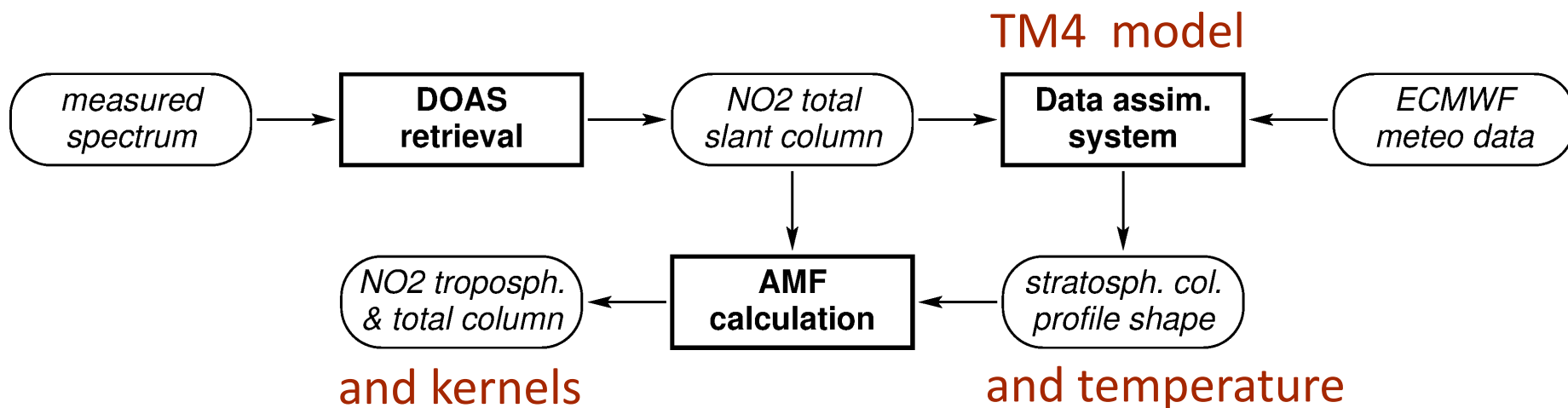
Currently, there is no standard for

Lingering smog C3

own satellite sending back images every half an hour." She said use of satellite images in re-

# The KNMI DOMINO NO<sub>2</sub> product

DOMINO: combined retrieval-assimilation system





## Developments NO<sub>2</sub> retrieval algorithm

- **DOAS spectral fitting**
- **Air-mass factor improvements:**
  - ◆ Use of TM5 model
  - ◆ O<sub>2</sub>-O<sub>2</sub> cloud retrieval
  - ◆ Error modelling update

# Improve solar reference spectrum

Update of high-resolution solar spectrum:

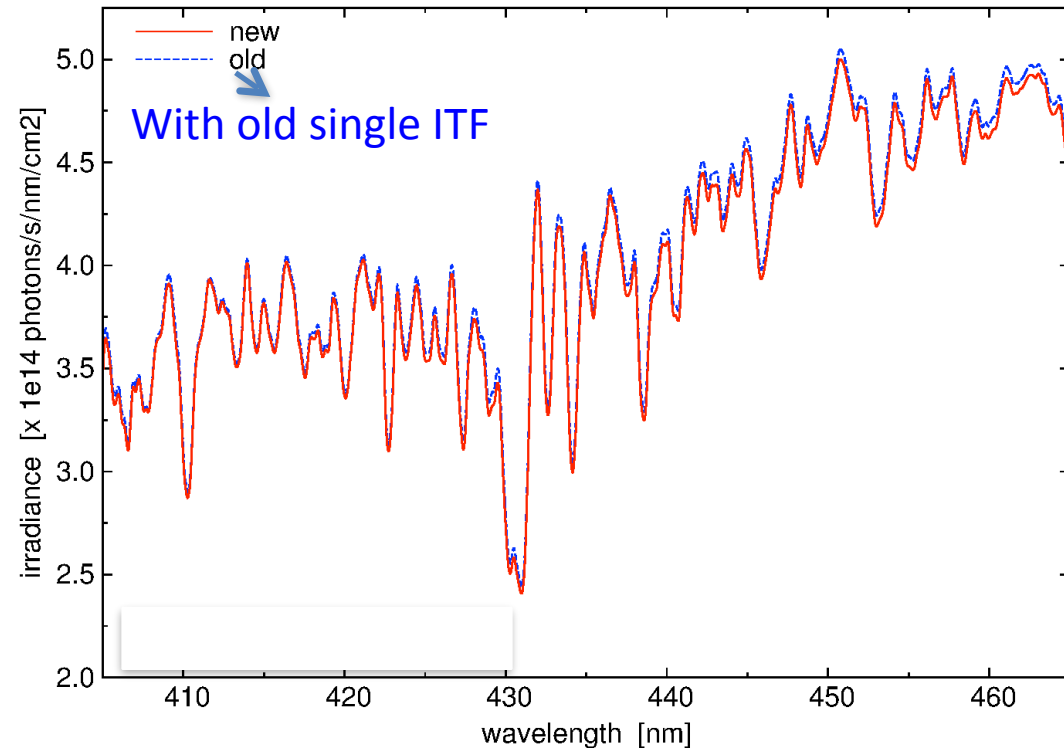
- better representation of OMI ITF (now  $\lambda$ -dependent)
- better Ring-spectrum and  $I_0$ -corrected reference spectra

New solar spectrum improves effective  $\lambda$ -calibration



RMS of fit: -17%

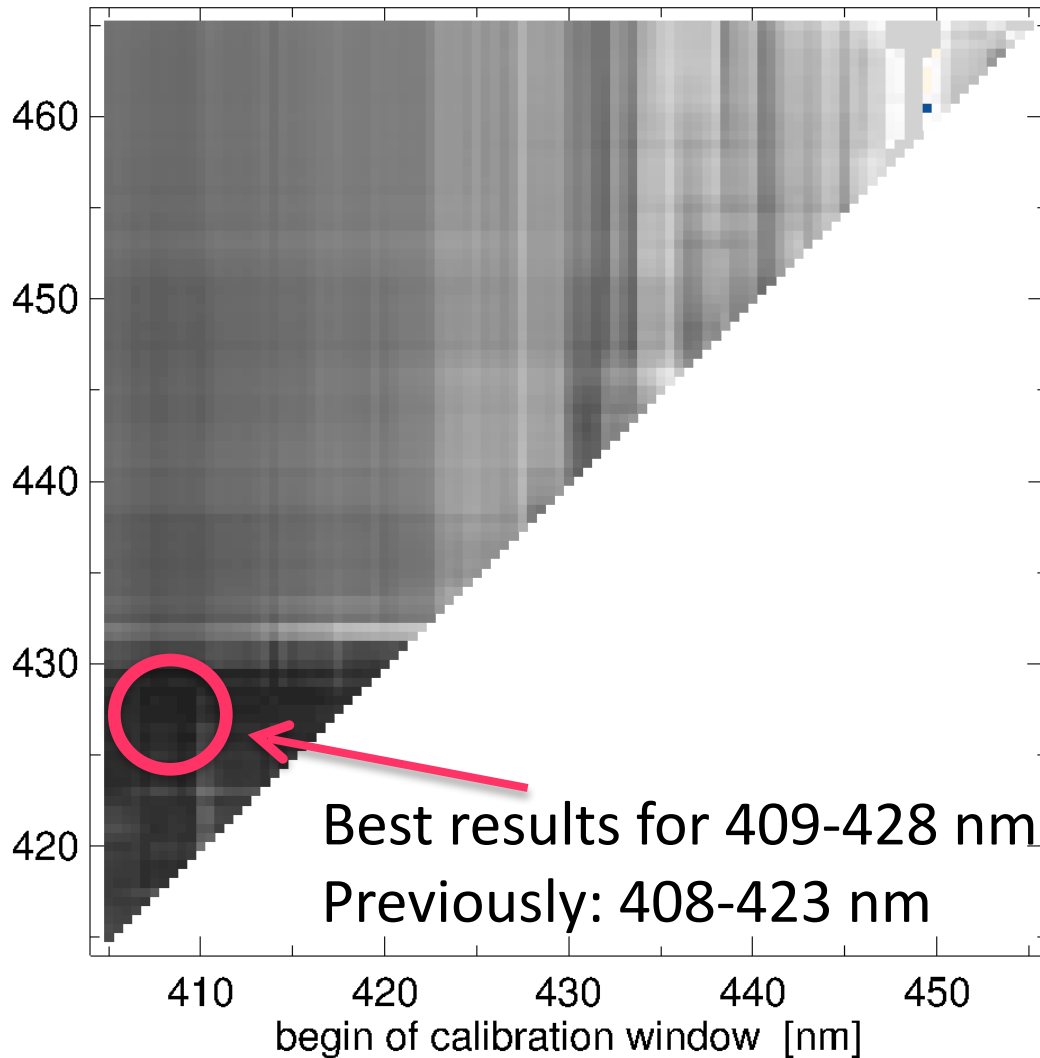
NO<sub>2</sub> slant columns: -6%



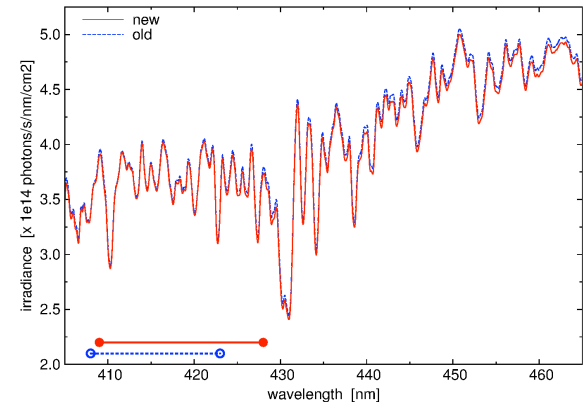
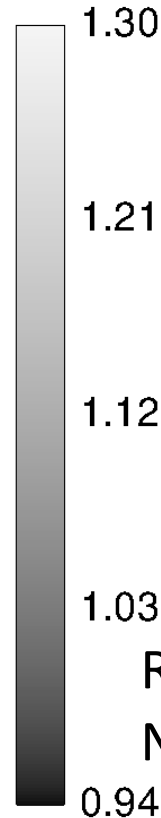
Other reference spectra otherwise identical to OMNO2A

# Improve $\lambda$ -calibration window to map $I$ to $I_0$

Identify  $\lambda$ -calibration window that minimizes RMS/ $\text{NO}_2$  fit error



RMS  
[ $\times 10^{-4}$ ]



RMS of fit: -32%  
 $\text{NO}_2$  slant columns: -13%



# Improve other reference spectra

NO<sub>2</sub>: still Vandaele et al. [1998] but with new ITF

O<sub>3</sub>: Bogumil et al. [2000] instead of obscure WMO-1975

H<sub>2</sub>O: HITRAN 2012 instead of HITRAN-2004

O<sub>2</sub>-O<sub>2</sub>: Now included!

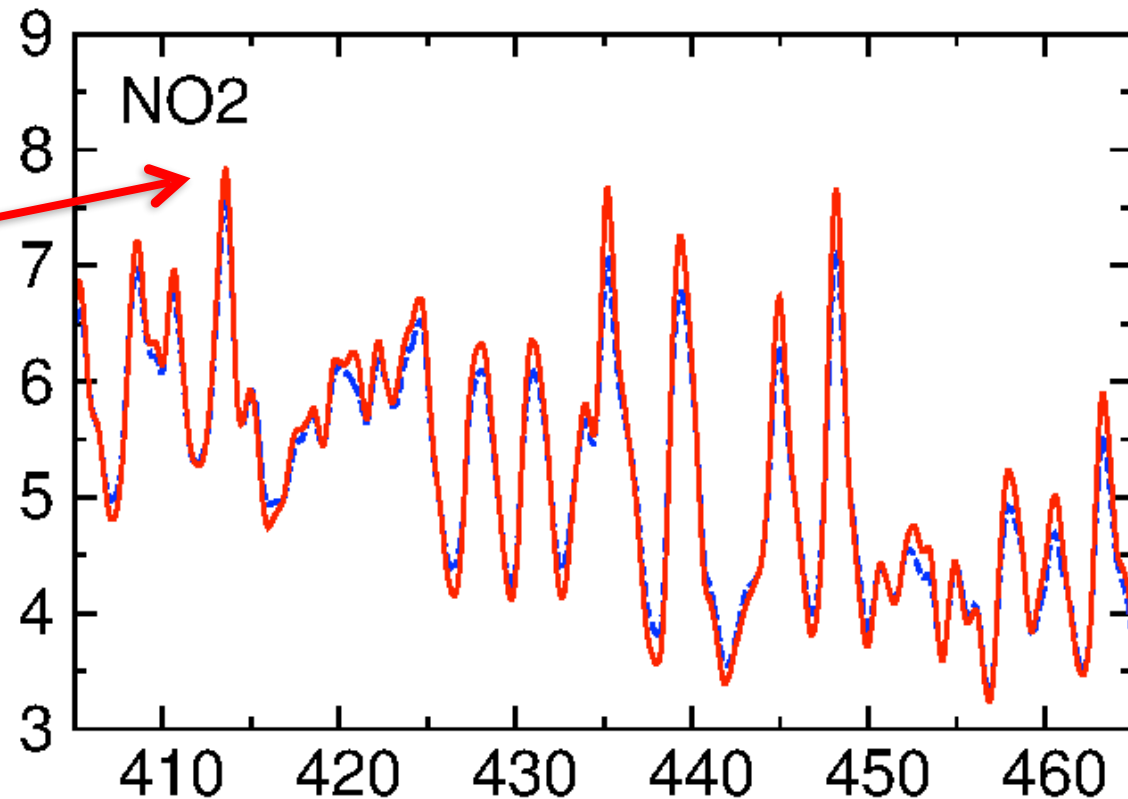
LQW: Now included!

Stronger amplitude in  
new NO<sub>2</sub> cross section!



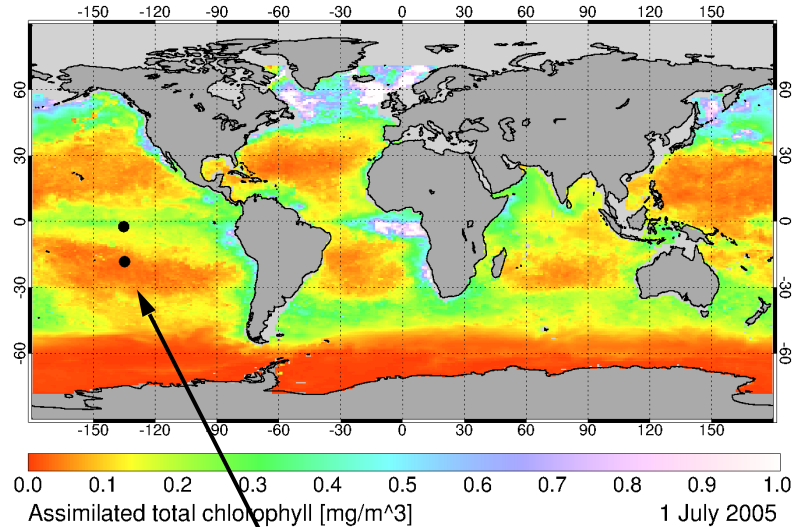
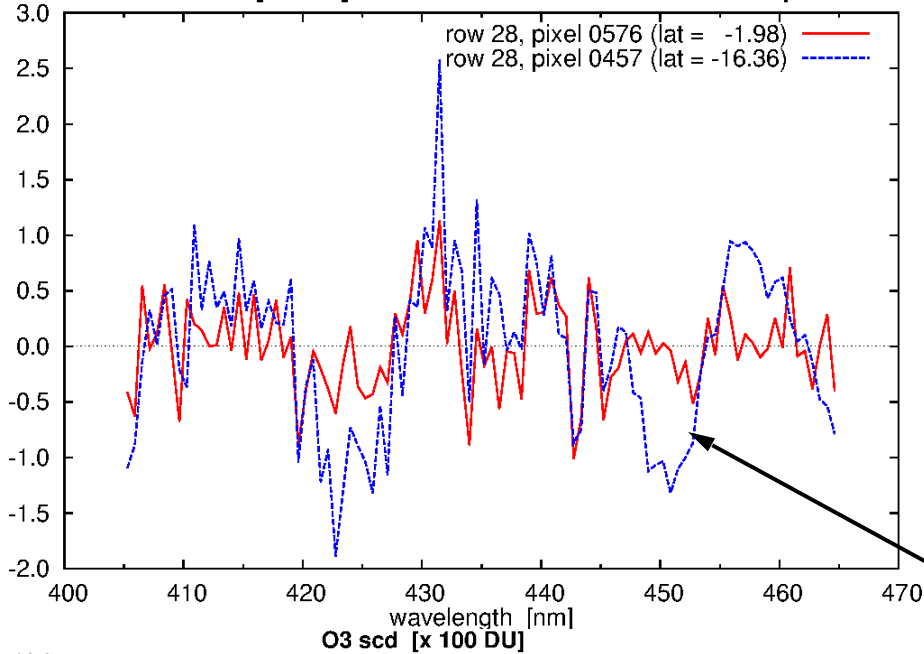
RMS of fit: -30%

NO<sub>2</sub> slant columns: -11%



# Including liquid water

Fit residual [x 1e-4] for cloud-free Pacific Ocean OMI pixels

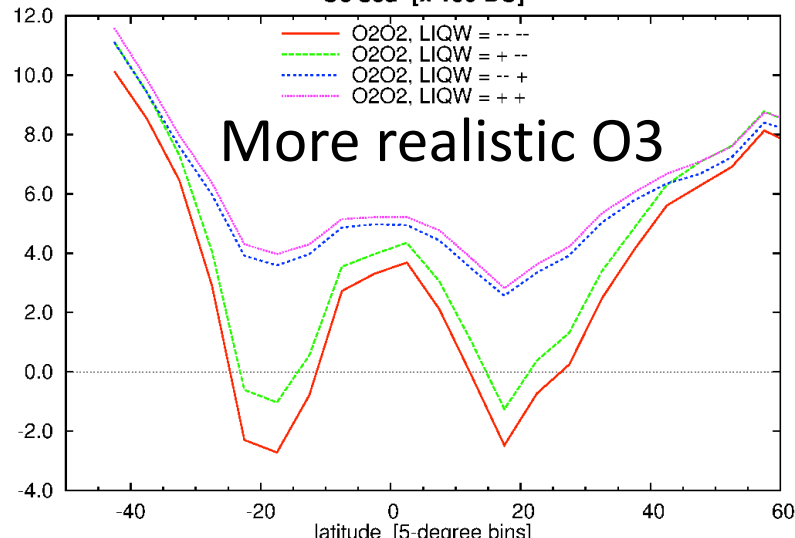


Strong feature for clear water pixel !

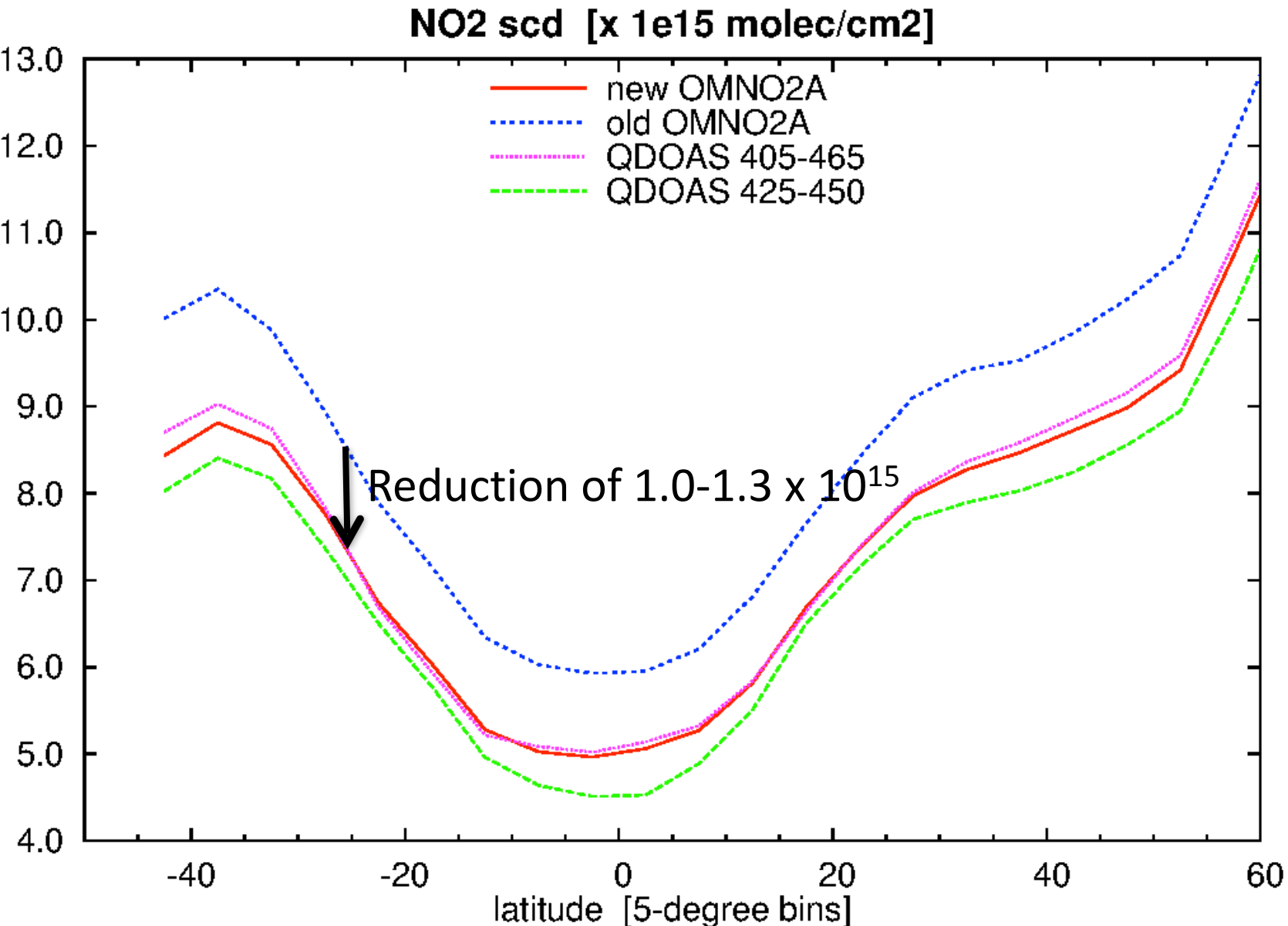
Fit results for cloudy pixels are not affected much when including liquid water absorption.

Including liquid water absorption in the  $\text{NO}_2$  fit is a good idea.

O3 scd [x 100 DU]



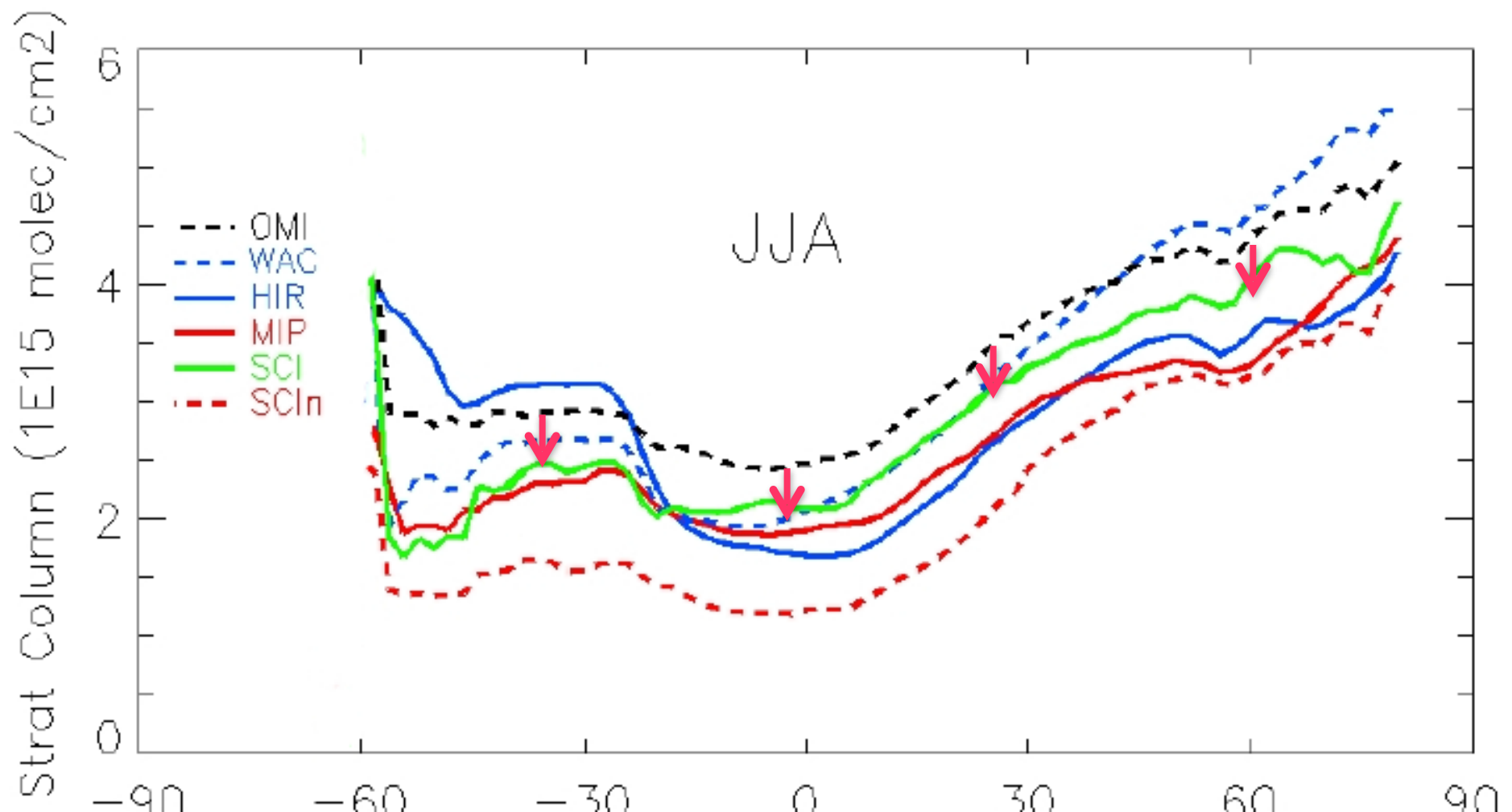
# Summary of the spectral fitting improvements





# Discrepancy between DOMINO v2 and limb sensors

A reduction of  $0.4\text{-}0.5 \times 10^{15}$  molec. $\text{cm}^{-2}$  would largely resolve the discrepancies with limb sensors (Belmonte Rivas et al., 2014)



## Developments NO<sub>2</sub> retrieval algorithm

- **DOAS spectral fitting**
- **Air-mass factor improvements:**
  - ◆ **Use of TM5 model**
  - ◆ **O<sub>2</sub>-O<sub>2</sub> cloud retrieval**
  - ◆ **Error modelling update**

# A new model for (TROP)OMI NO<sub>2</sub> retrievals

DOMINO v1 and v2: based on TM4 at 3° × 2°

DOMINO v3: based on TM5 at 1° × 1°

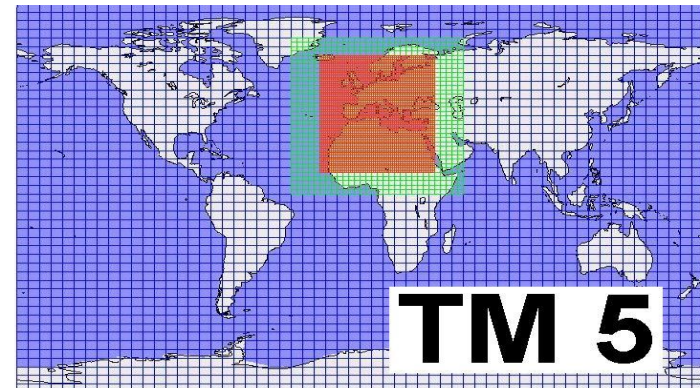
## Motivation:

- TM5 is benchmarked (Huijnen et al., 2010)
- Parallel code: allows 1° × 1°
- Extended chemistry (CB05 scheme)
- Employs up-to-date emission inventories



Bram Maasackers, M.Sc

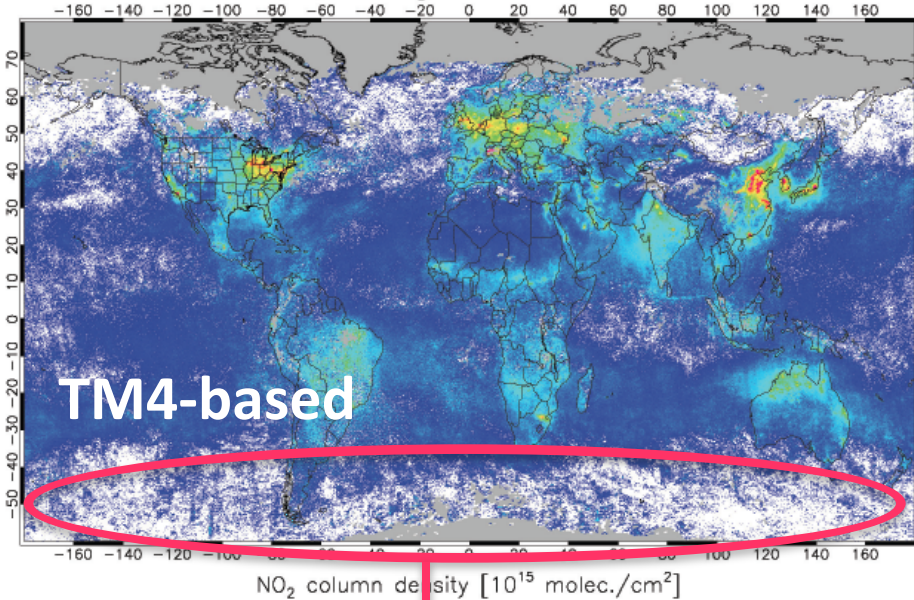
Note: TM5 2005 model data available  
for TROPOMI teams





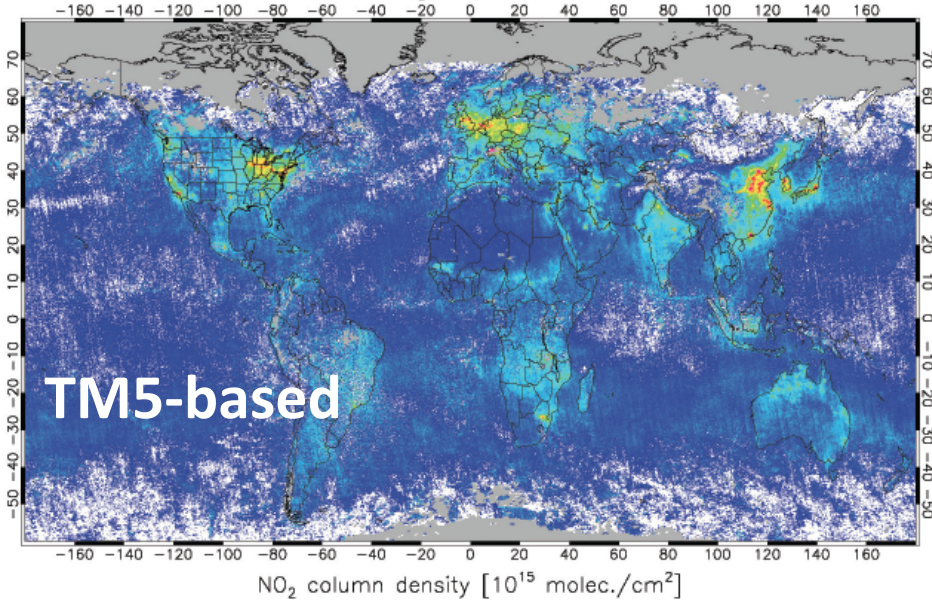
# Impact on the stratosphere

OMI tropospheric NO<sub>2</sub>, TM4 retrieval, 20-30 Oct 2004



TM4-based

OMI tropospheric NO<sub>2</sub>, TM5 retrieval, 20-30 Oct 2004



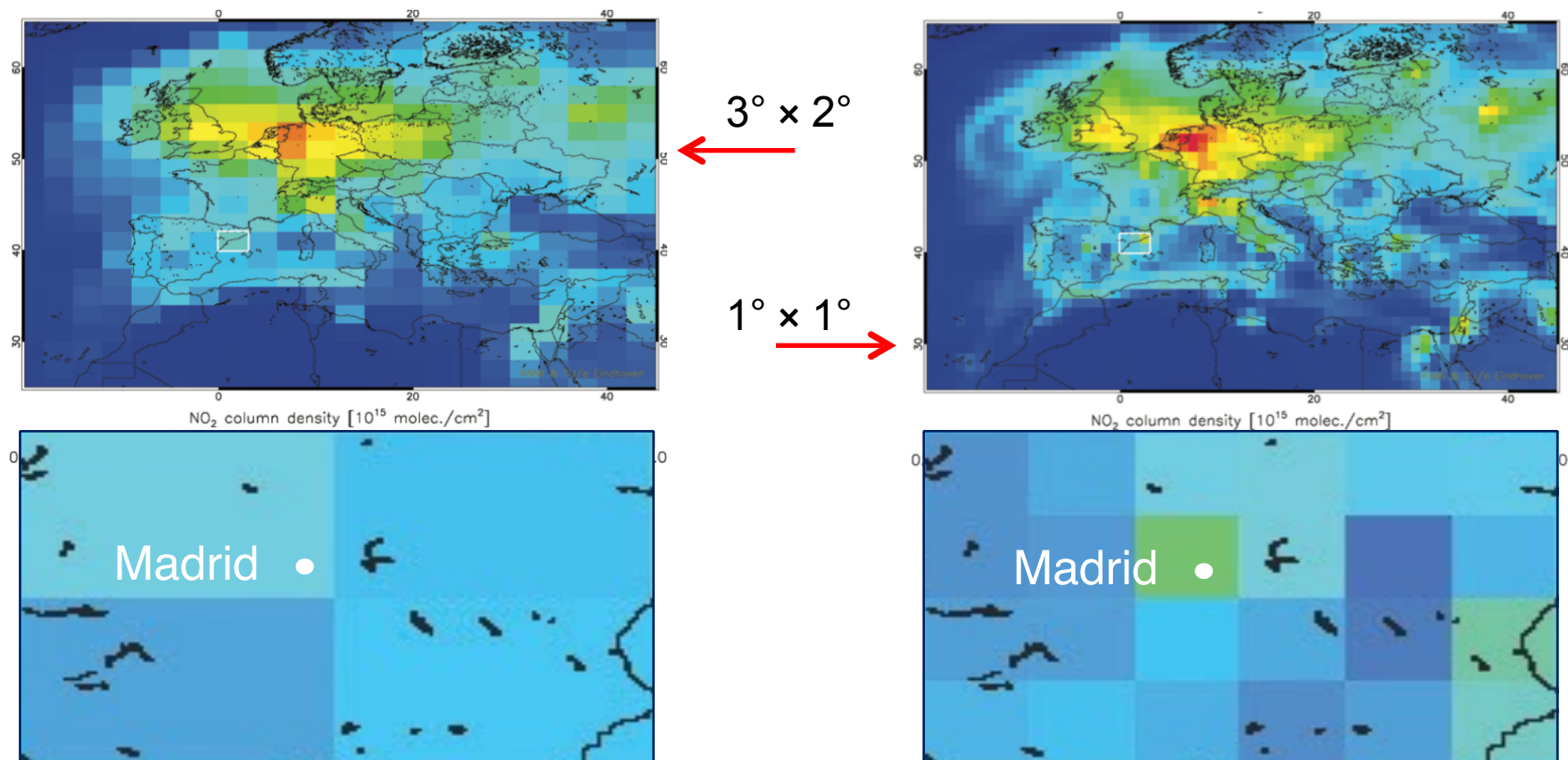
TM5-based

White areas: negatives

With new TM5: 27% fewer negatives

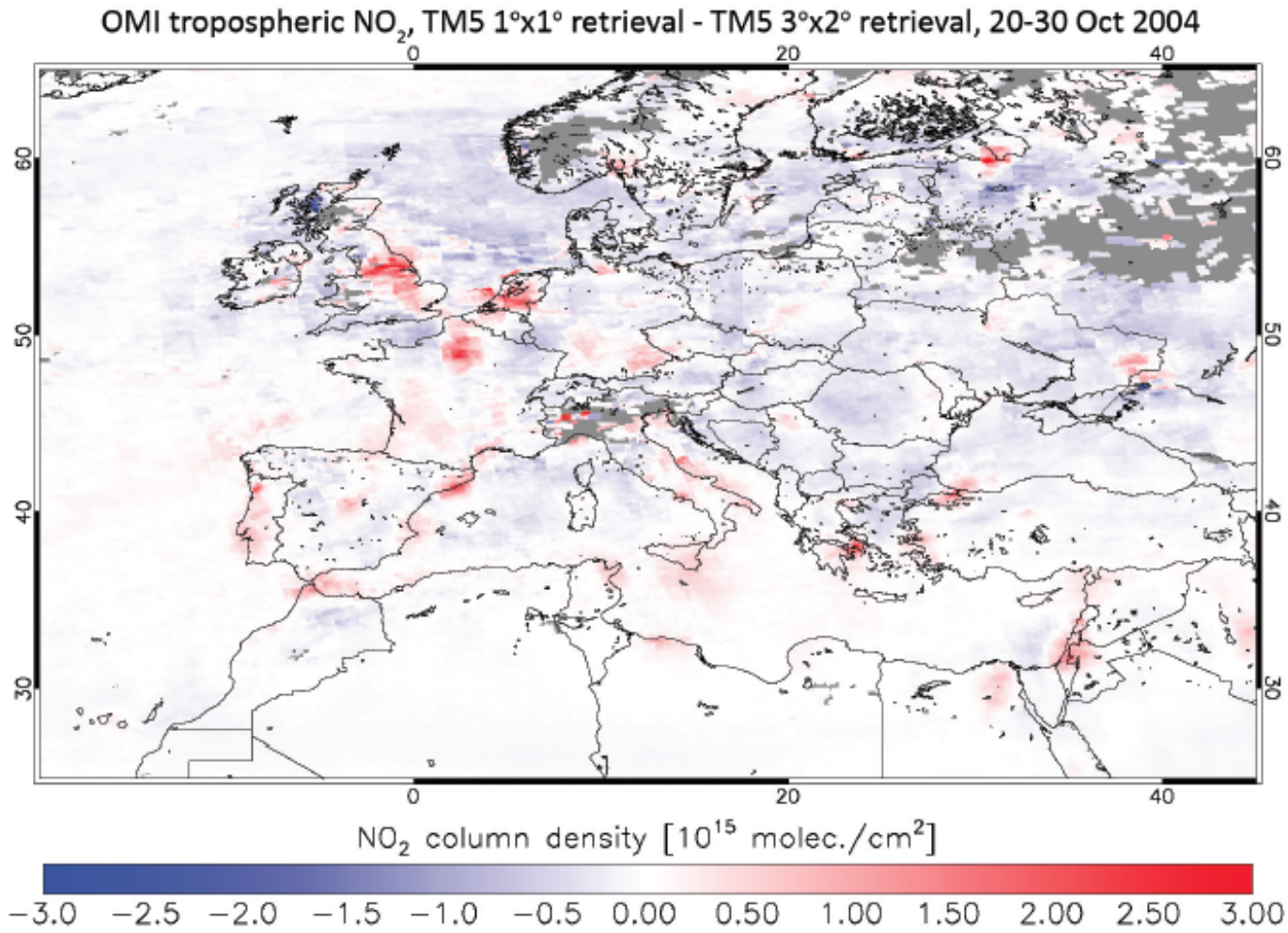
# Increasing resolution to $1^\circ \times 1^\circ$

Better resolved a priori profile shapes lead to a better understanding of pollution gradients observed from space





# DOMINO with TM5 at $1^\circ \times 1^\circ$ vs. at $3^\circ \times 2^\circ$



Increase of the urban-to-rural contrast !

## Developments NO<sub>2</sub> retrieval algorithm

- **DOAS spectral fitting**
- **Air-mass factor improvements:**
  - ◆ **Use of TM5 model**
  - ◆ **O<sub>2</sub>-O<sub>2</sub> cloud retrieval**
  - ◆ **Error modelling update**

# Systematic error in O<sub>2</sub>-O<sub>2</sub> cloud pressures

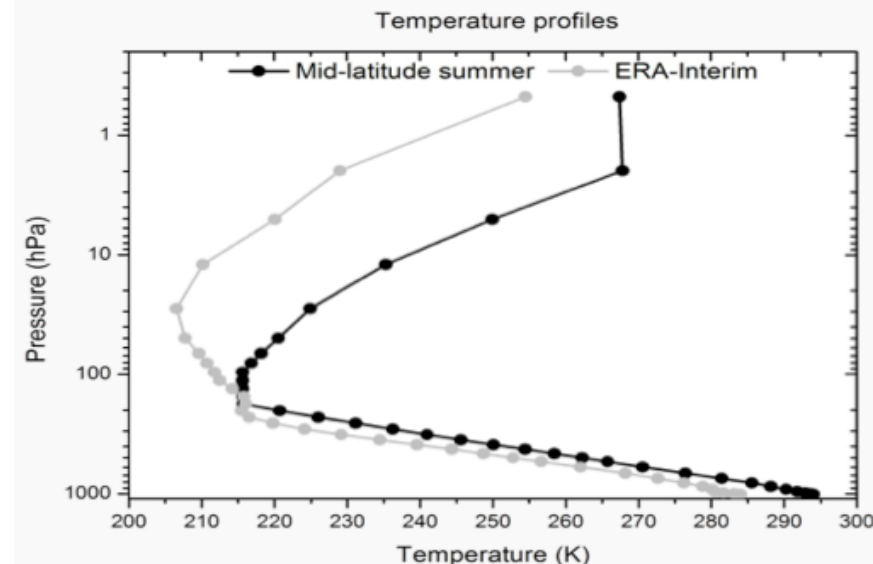
- Retrieved O<sub>2</sub>-O<sub>2</sub> slant column depends on atmospheric temperature profile

$$I(\lambda) = I_0(\lambda) \exp \left( - \int_{z_c}^{z_{TOA}} m(z, \lambda) n_{O_2}^2(z) \sigma_{O_2-O_2}(\lambda) dz \right)$$

$n^2 \sim 1/T^2$

$\sim T_{dp}$

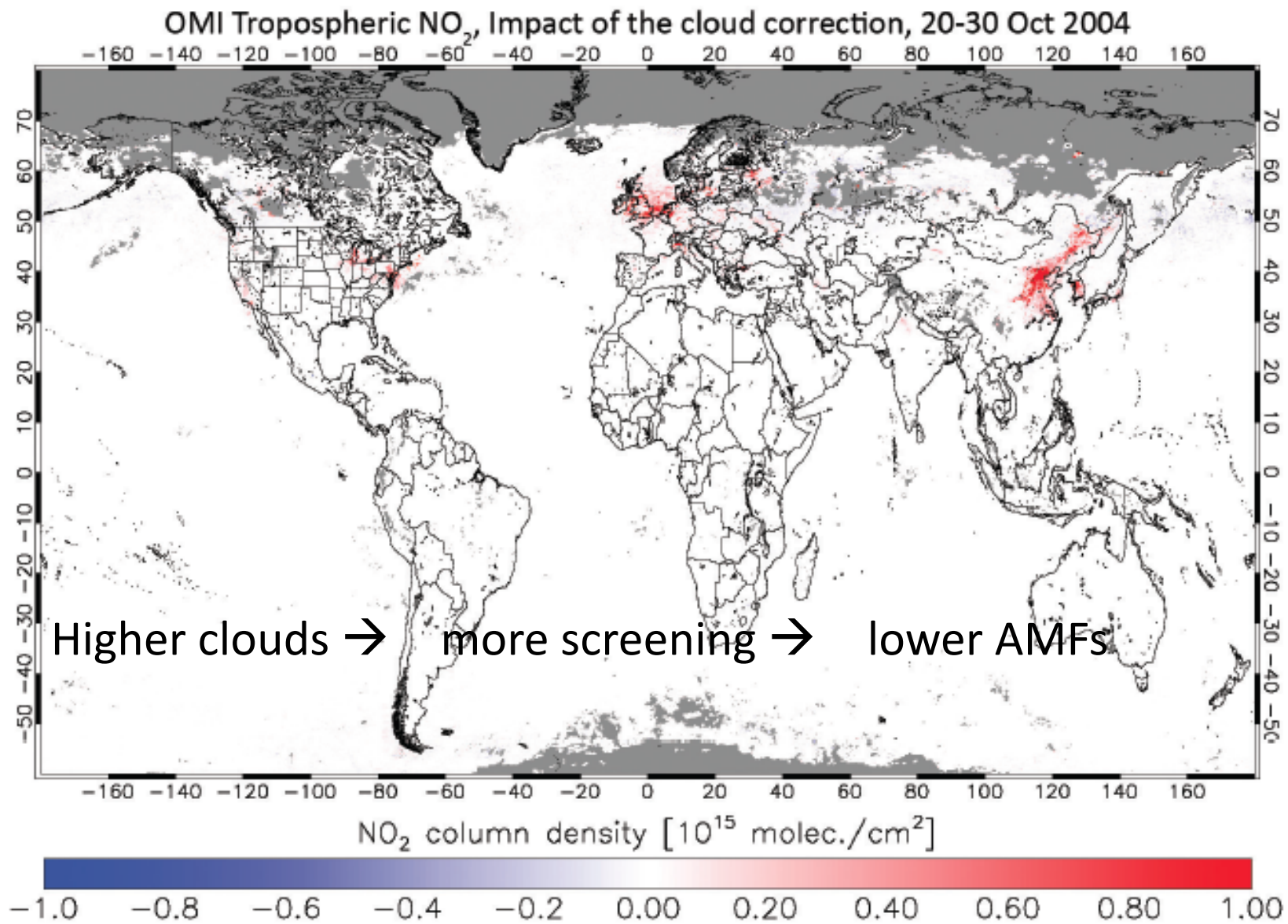
- LUT for O<sub>2</sub>-O<sub>2</sub> based on fixed AFGL mid-latitude summer T-profile
- O<sub>2</sub>-O<sub>2</sub> slant columns require T-correction since 'true' T profile may differ strongly from mls-profile



*Acknowledgment: Johan de Haan*

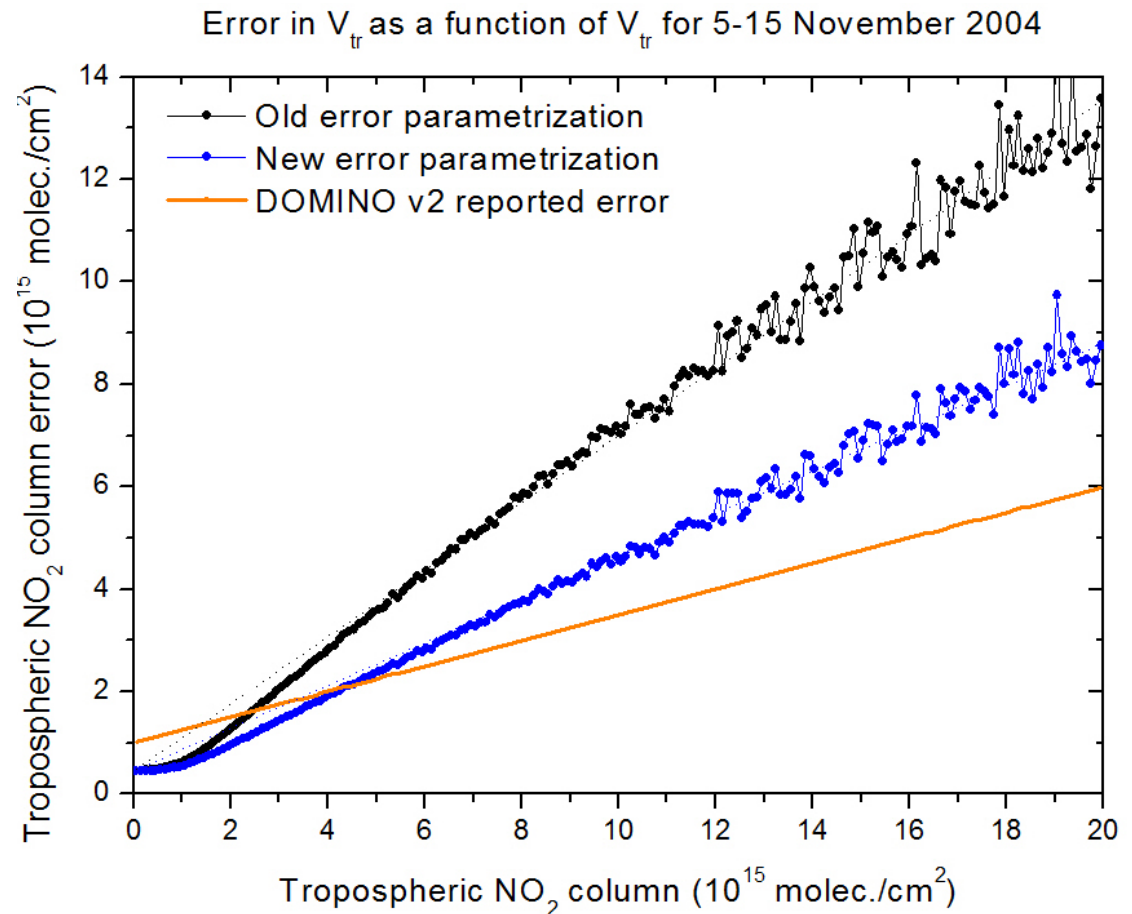


# Impact on NO<sub>2</sub> retrievals of O<sub>2</sub>-O<sub>2</sub> improvement



# Refined error modelling

Update of error modelling inputs:  
cloud fraction error, albedo error, profile error,  
stratosphere error, slant column error



## Ongoing work

- ◆ Preparing for DOMINO-v3 re-processing of OMI
- ◆ Preparing the TROPOMI NO<sub>2</sub> algorithms
  - Near-Real Time
  - Assimilation-Retrieval
- ◆ Preparing for QA4ECV reprocessing of NO<sub>2</sub> for multiple sensors

## Conclusions: DOMINO-2 → DOMINO-3

- Improved NO<sub>2</sub> slant columns are smaller by 1.0-1.3 10<sup>15</sup> molec.cm<sup>-2</sup> with 30% lower fitting residuals
- Coupled DOMINO to TM5-mp (2015 version)
- Improved resolution for a priori profile leads to increases over hotspots (+20%) and stronger contrast urban-rural
- Temperature-correction for cloud pressures relevant over polluted areas

**(TROP)OMI NO<sub>2</sub> team from 2014 onwards:**

