## SBAS-DInSAR processing chain for Interferometric Wide Swath Sentinel-1 data

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## **SBAS-DInSAR Block Diagram**



<u>Orbit Registration</u>: Rigid offset, it is retrieved in one point exploiting orbit and target location (DEM) information.

<u>Coherence Maximization</u>: Rigid offset, it is retrieved in one patch by maximizing the number of coherent points

<u>Geometric Registration</u>: it is performed point by point, using orbit and location (DEM) information

<u>Spectral Diversity Compensation</u>: the residual phase, estimated through Spectral Diversity method, is compensated directly from interferograms, without performing again the interpolation of slave images.



## S-1A Commissioning Phase























## **Orbit Information: Annotated vs. External**

External: 10-sec State Vectors

Annotated: 1-sec State Vectors

Annotated Orbit are generated by exploiting External Orbit

Acquisition Date	Annotated Information		External Information (S1A_OPER_AUX_RESORB)	
	Orbit	Coherence	Orbit	Coherence
20-10-2014	0.0	0.0	0.0	0.0
01-11-2014	6.806	6.981	6.963	6.996
13-11-2014	1.546	1.296	1.276	1.293
25-11-2014	7.110	7.335	NA	NA
Mean Error	0.21		0.02	



## **SBAS-DInSAR Block Diagram**



## SBAS approach: key points



- exploiting interferograms characterized by a "<u>small baseline</u>" in order to limit the noise (decorrelation) phenomena, thus maximizing the number of investigated pixels;
- using <u>no *a priori* or model information</u> on the investigated
   deformation signal;
- PhU operation is usually performed by applying MCF or EMCF
   techniques.

#### Achieved accuracies:

- • ≈ 1 2 mm/year on the mean deformation velocity
- $\approx$  5 10 mm on the single displacement



## S-1A SBAS approach: pair selection

Orbital tube of Sentinel-1 should be very short, therefore no perpendicular baseline constraint needs to be applied.

To get redundancy of interferograms, each acquisition is coupled with the 3 following scenes in time.

The number of interferograms is about 3\*(Number of acquisitions)





**Acquisition Time** 

#### TOPS SBAS results: RS2 TOPS campaign over Mexico City

	Baseline		
Acq. Time	Perp. [m]	Parallel [m]	Along track [m]
04042013	-27	-30	14
28042013	-120	-98	-13
22052013	-65	-53	-22
15062013	70	30	-12
09072013	129	81	-13
02082013	0	0	0
26082013	-117	-99	8
19092013	50	-36	10
13102013	-35	-103	29
06112013	124	21	20
30112013	-23	-82	9



### TOPS SBAS results: RS2 TOPS campaign over Mexico City

RS2 TOPS interferograms show good coherence (24 days revisit time)

Several RS2 TOPS scenes are affected by significant orbit errors





Azimuth

#### RS2 TOPS interferograms: orbital parameter correction



#### RS2 TOPS interferograms: orbital parameter correction



### RS2 TOPS interferograms: orbital parameter correction



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#### TOPS SBAS results: RS2 TOPS campaign over Mexico City



## Upcoming step: Big Data processing

**ESA archives** have guaranteed large availability of ERS-ENV scenes



ENVISAT coverage over Italy 2003-2010 Only ascending tracks



ENVISAT coverage over California and Nevada 2003-2010 Only ascending tracks

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# ≈ 150 Frames x 4 Nodes for frame ≈ 600 Nodes≈ 1 day



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## ESA-Grid Processing on Demand (G-POD)



## **G-POD computing facilities**

- Currently, computing facilities at ESRIN and UK-PAC
- more than **350 CPUs in**
- about 70 Nodes
- **330 TB** of local on-line Storage
- internal dedicated 1 Gbps LAN
- **1 Gbps** for external connection
- Globus software on Linux



- Thanks to the flexibility of the GRID architecture, G-POD can easily federate additional computing and storage resources, also in Cloud environments
- CNR-IREA nodes recently federated



## **G-POD Web Portal of P-SBAS service**





