

## → POLINSAR 2015

# A new light on misclassification results on the SOMA district in San Francisco due to the difficulty to predict entropy

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(1)

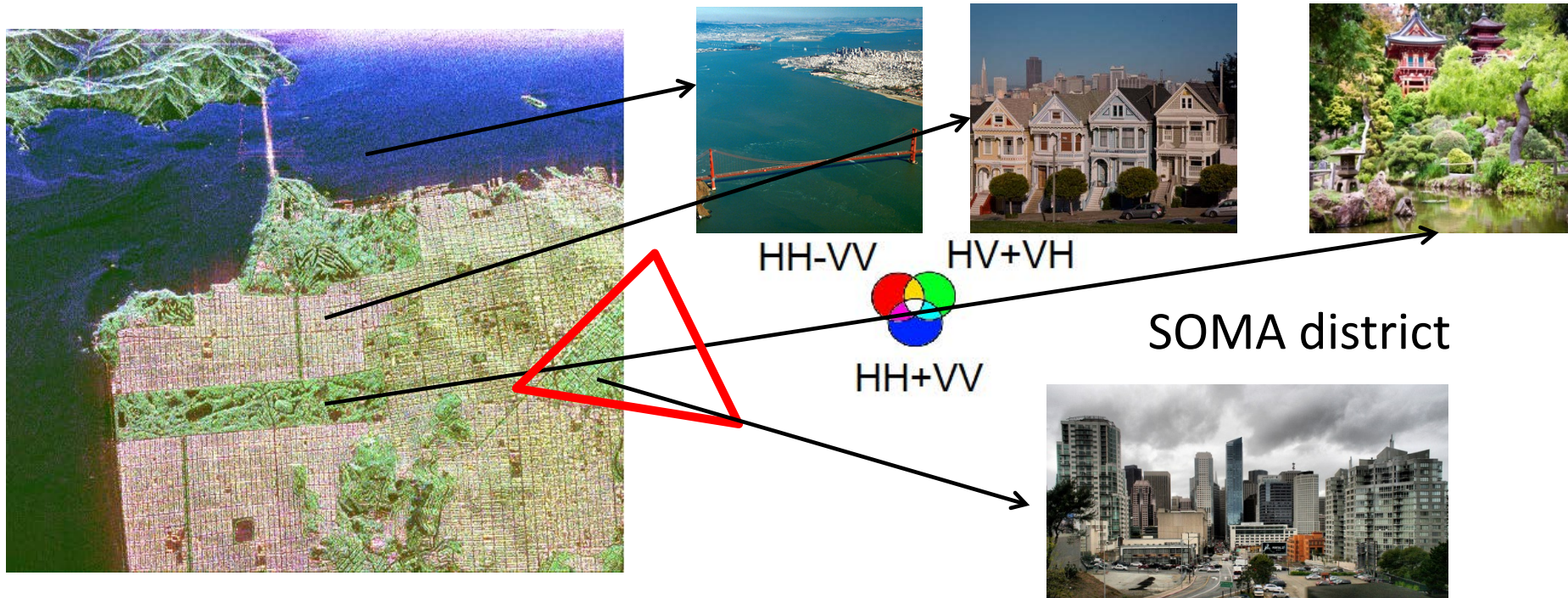


(2)

26–30 January 2015 | ESA–ESRIN | Frascati (Rome), Italy



# The general problem to solve



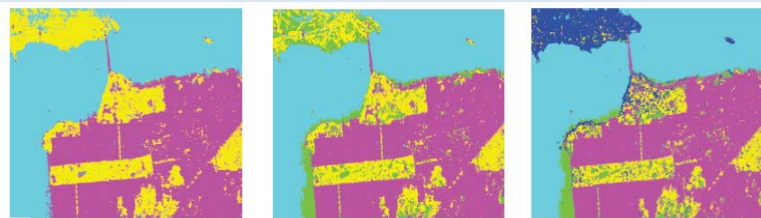
We know that HV signal is high because of orientation effects,  
but we are not able to fully compensate them



# The general problem to solve



Misclassification results



*Recent Polarimetric classification results using machine learning*



Poor detection results

*Results obtained during POLSARAP  
Built-up areas detection*



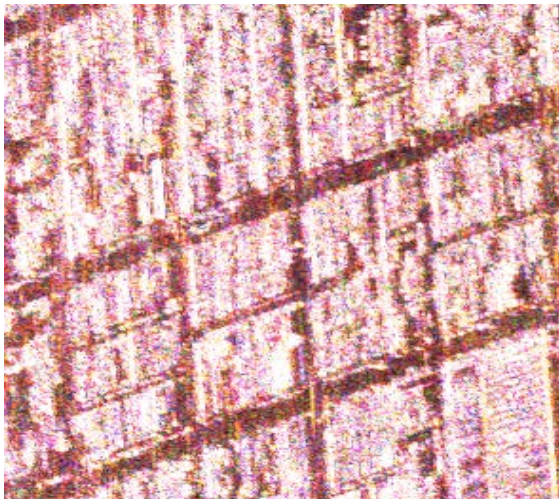
# What here?



- Further insights into urban effects
  - About HV signal and orientation of streets
  - About Entropy and its spatial estimation

Streets aligned with the trajectory

**HV is low**  
**entropy is low**



HH-VV

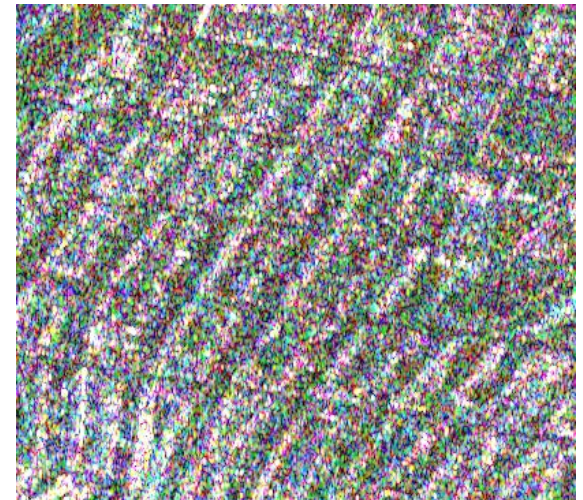


HV+VH

HH+VV

Streets not aligned with the trajectory

**HV is high**  
**entropy is high**

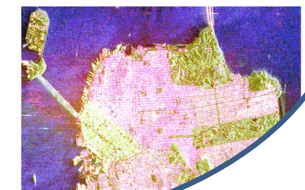
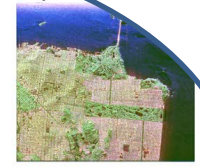
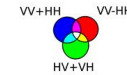
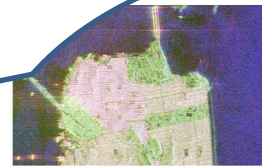




# How ?



Image  
Analysis



Statistical  
simulation

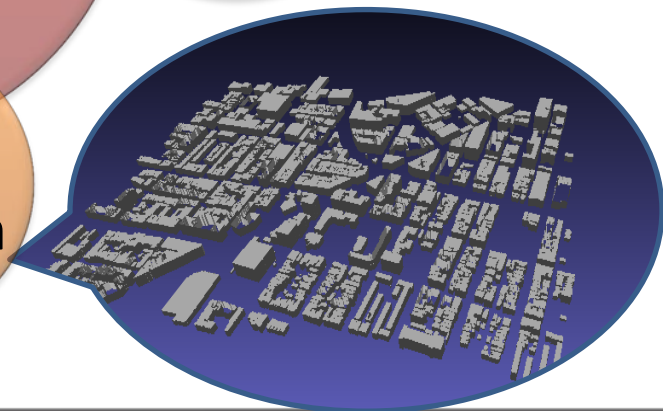
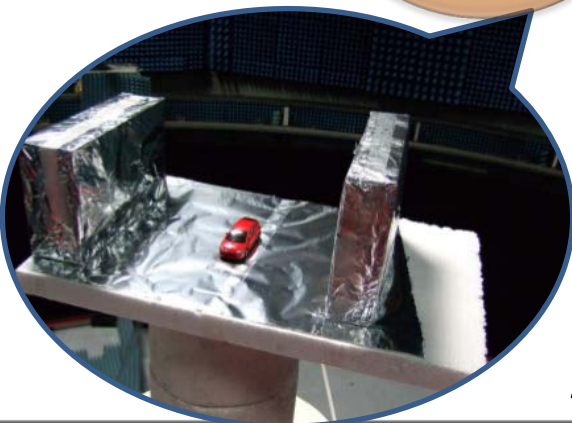
PhD  
Flora Weissgerber

Understanding  
physics  
behind the signal

Scaled  
measurements

EM  
simulation

PhD  
Azza Mokadem



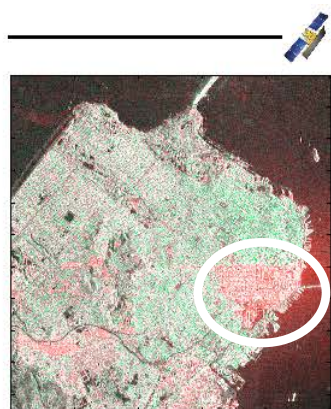
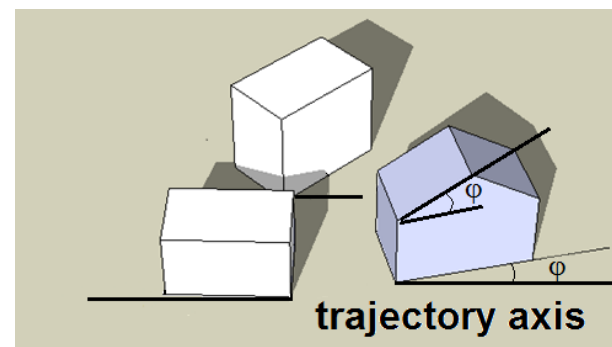


# The problem with HV

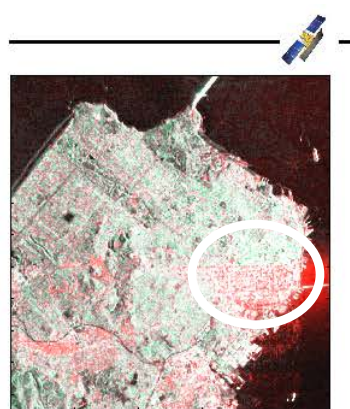


Oriented target = signal in HV channel

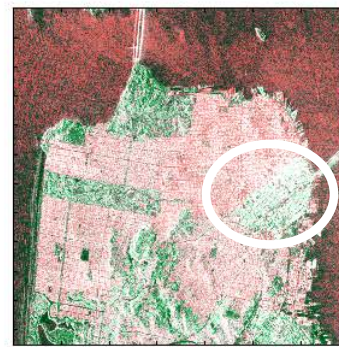
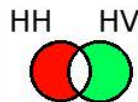
Many oriented targets in urban areas:  
roofs, dihedral corner non oriented along  
trajectory axis



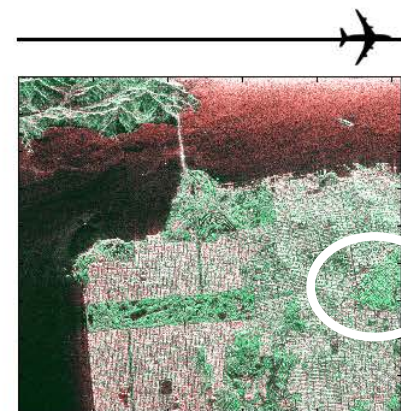
L-band, SIR-C



C-band, SIR-C



C-band, RADARSAT-2



L-band, AIRSAR

Deorientation :

rotation around the wave direction to align the target axis along H-axis



# Difficulty to compensate orientations



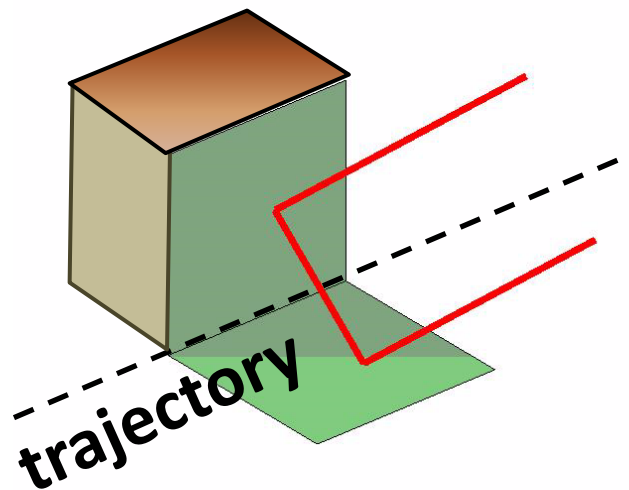
## Not so simple

- A dielectric corner is not a metallic corner
- The axis orientation is projected from a 3D element onto a 2D plane

Orientation of a dihedral corner  $\phi$   
 $\neq$  polarimetric orientation angle



Example : what does a street becomes after a  $45^\circ$  polarimetric basis rotation?



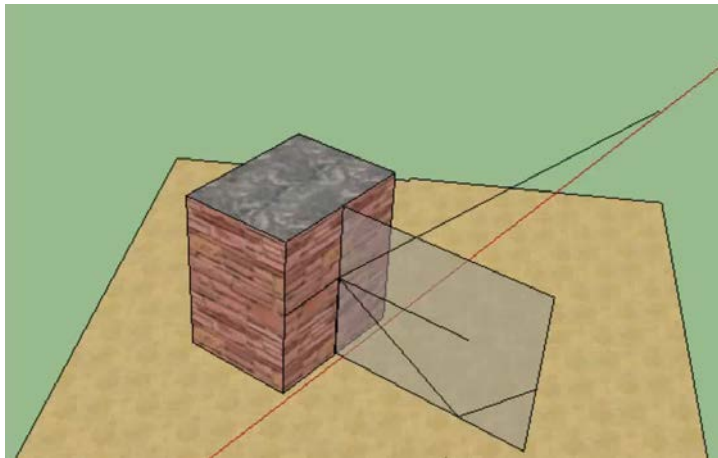


# Difficulty to compensate orientations



## A street along trajectory

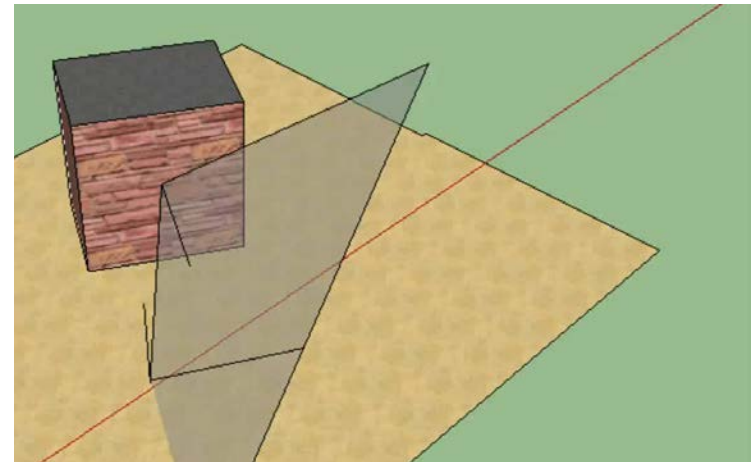
The double bounce mechanism for a wall oriented along the trajectory involves two specular reflections



**HH-VV very high !**

## Any street orientation

Only one possible specular reflection



**HH-VV lower, no principal mechanism**

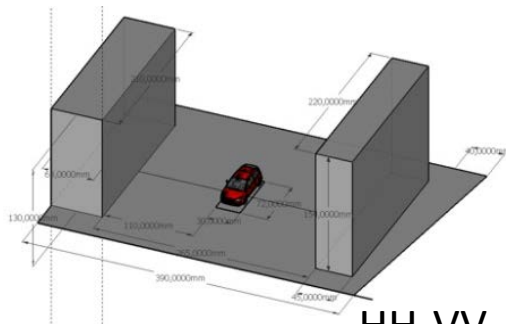


# Entropy and orientation : EM simulations

## Results of exact modelling / indoor measurement

- When orientation increases
  - The double bounce effect is not more predominant
  - All mechanisms contribute, and entropy increases because the mixture becomes spatially random

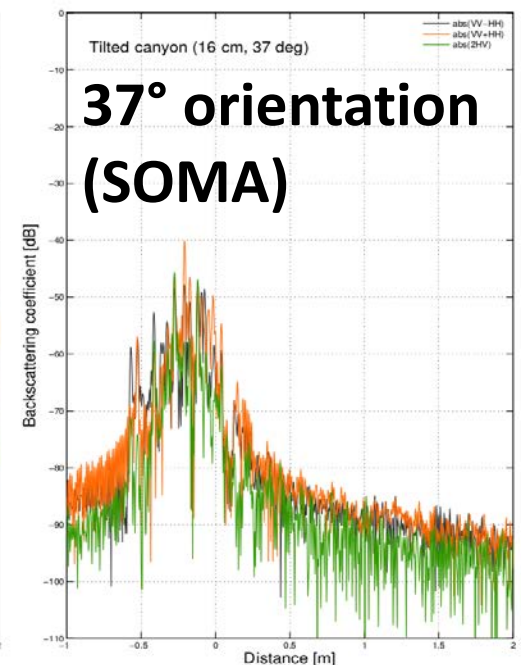
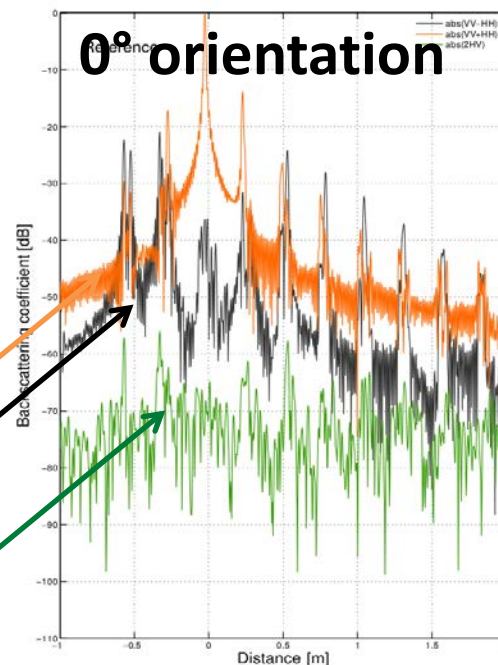
Results presented in EUSAR 2014  
[Thirion Lefevre et al.]



HH-VV

HH+VV

HV+VH





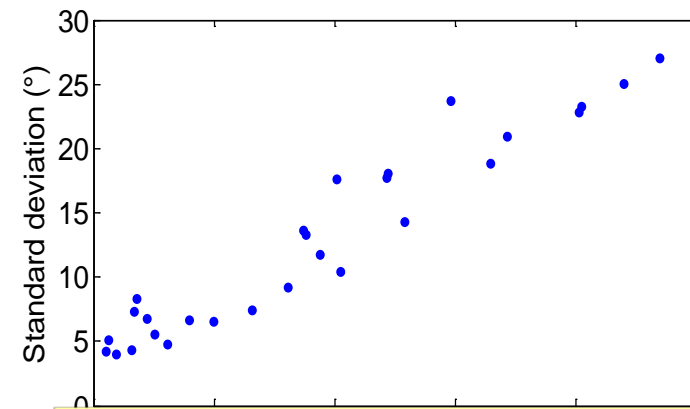
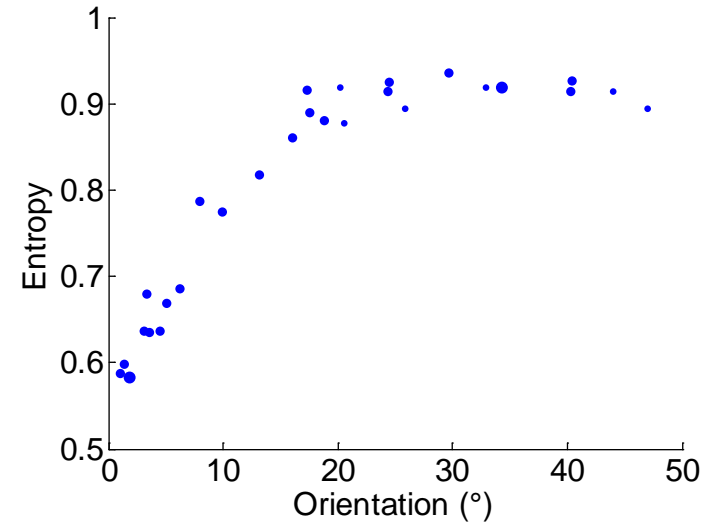
# Entropy and orientation: images



Courtesy of UAVSAR,  
New Orleans



- When orientation increases, entropy rapidly increases
- Saturation effect from 20°



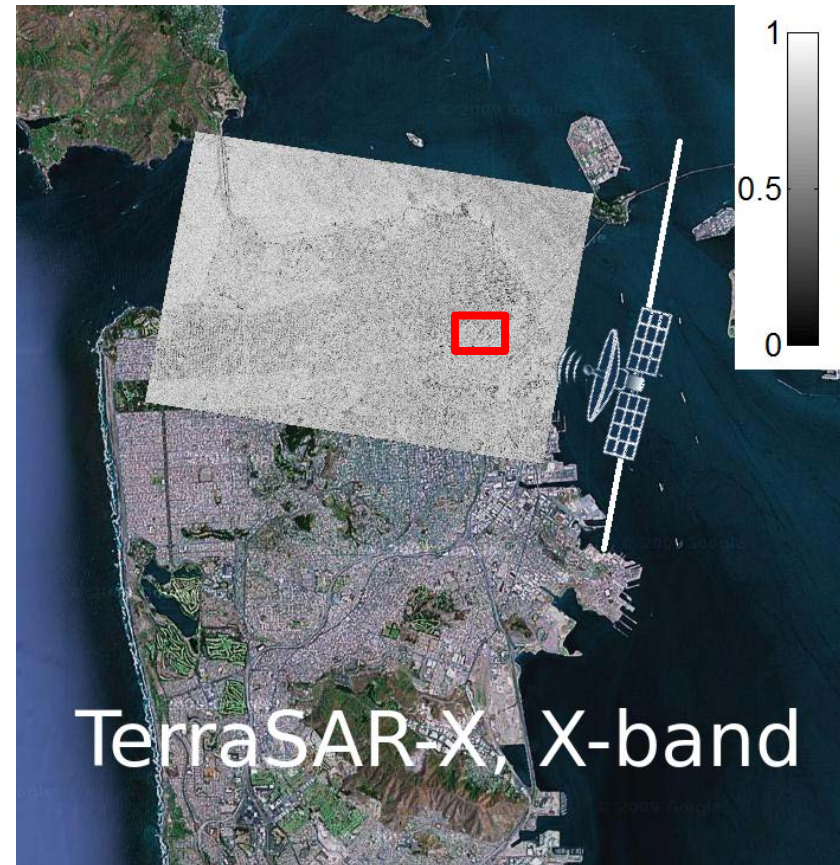
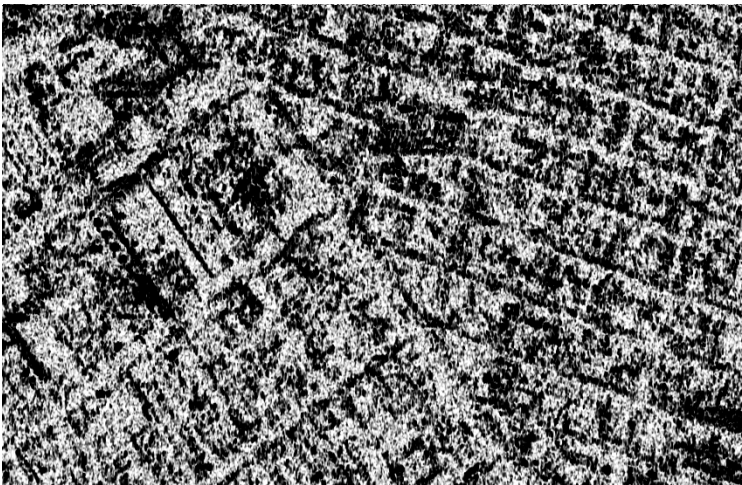
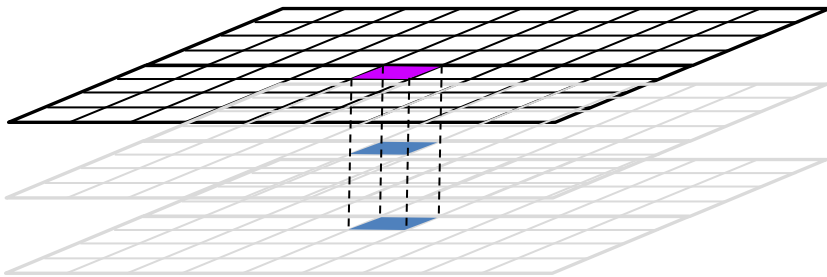
Polarization Orientation angle



# Entropy and resolution



- 3 TerraSAR-X images

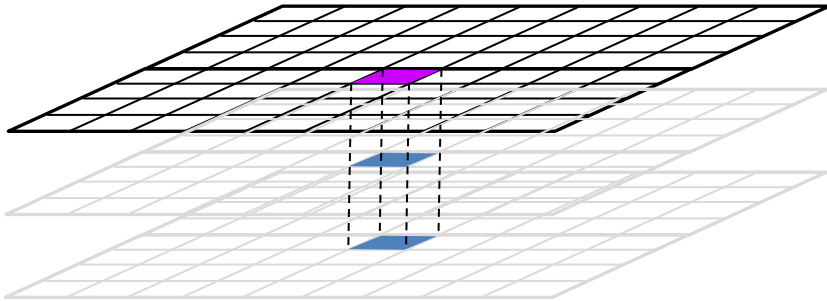




# Entropy and resolution



- 3 UAVSAR images



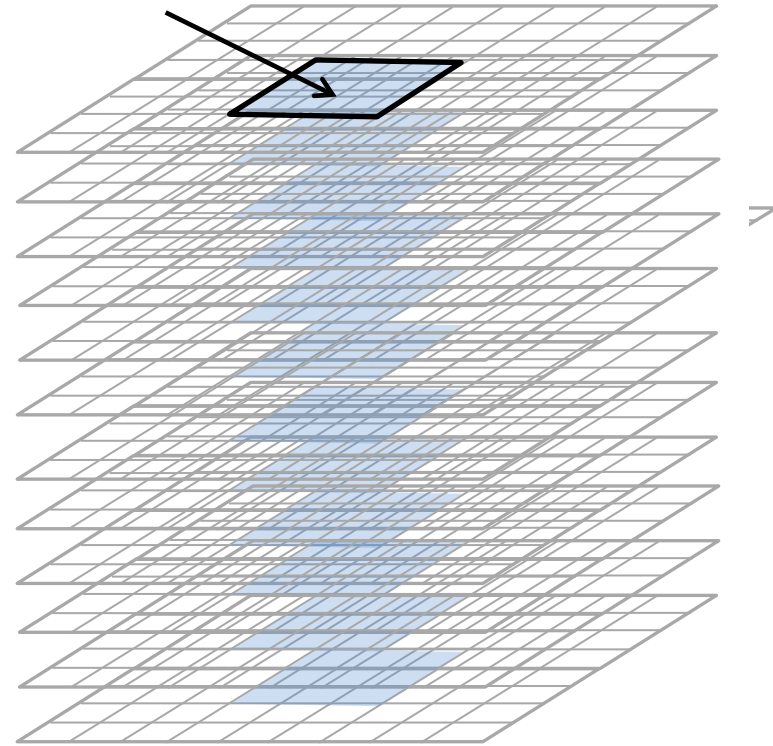


# Temporal estimation

- 12 UAVSAR multilook images



1 multilook pixel



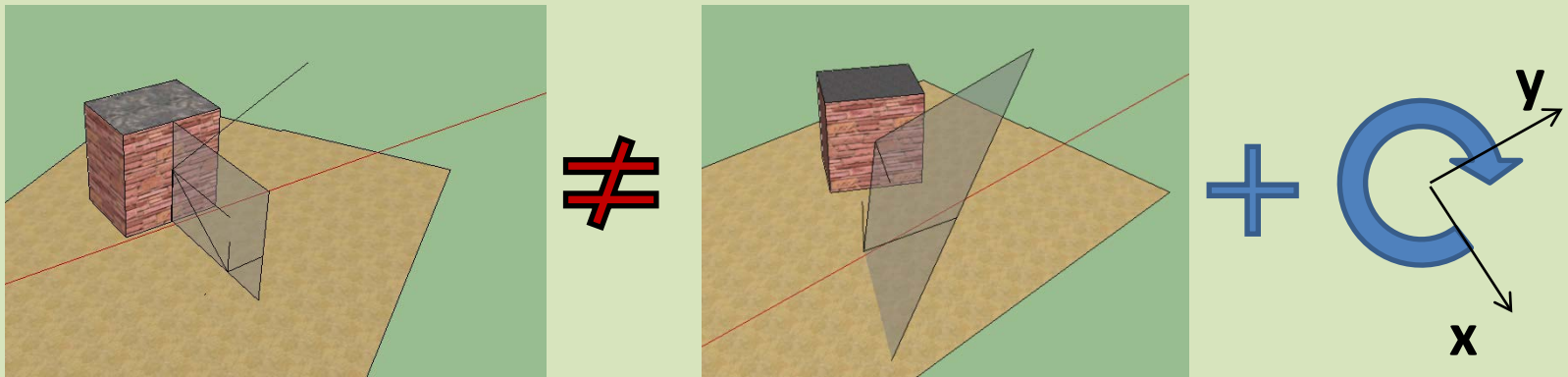
12 images



# Summary: why misclassification

## Misclassification linked to first order parameters

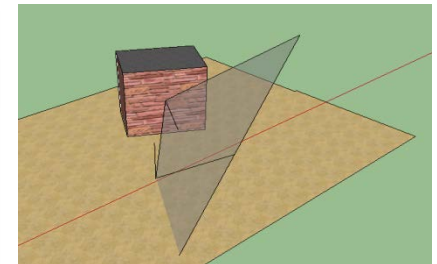
- When orientation of street increases, the double bounce mechanism is completely different from the well oriented ones



- Deorientation does not mean we are able to retrieve the signal when the scattering plane is colinear to the symmetry plane

## Recommendations

- Specific modelling and specific representations in decompositions





## Misclassification linked to statistical estimation

- **When orientation of street increases, entropy increases**, because amplitude of a dihedral desoriented effect is not as strong as the well oriented ones
- When statistical estimation is required, **spatial estimation is not effective in urban**, especially for some resolutions ( around 1 m) because mixes different polarimetric parameters

## Recommendations

Towards temporal estimation.

There are very **promising results** using only 3 images.

**Any help for UAVSAR SLC processing data request ?**

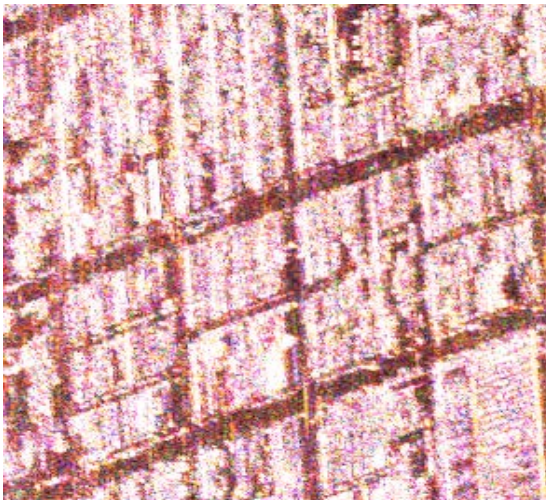


# Summary



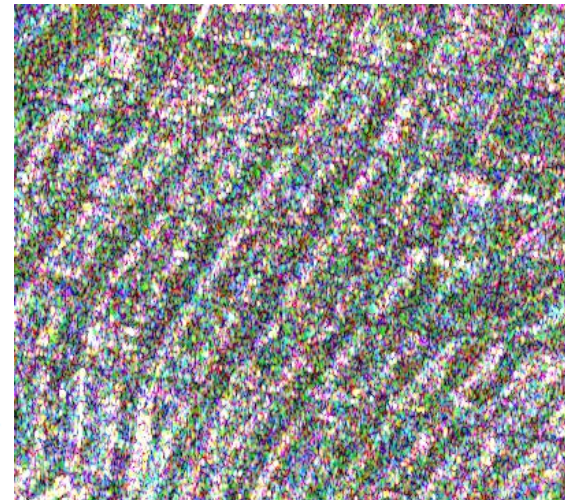
## Streets aligned with the trajectory

- Double bounce effects are higher than other contributions. They are predominant
- If the entropy is estimated spatially, the strong intensity makes the double bounce mechanism dominant
- As the main mechanism remains the same entropy is low



## Streets not aligned with the trajectory

- All mechanisms have comparable amplitudes
- Rotation cannot change this feature
- If entropy is performed by a boxcar filtering, it is high





# To conclude

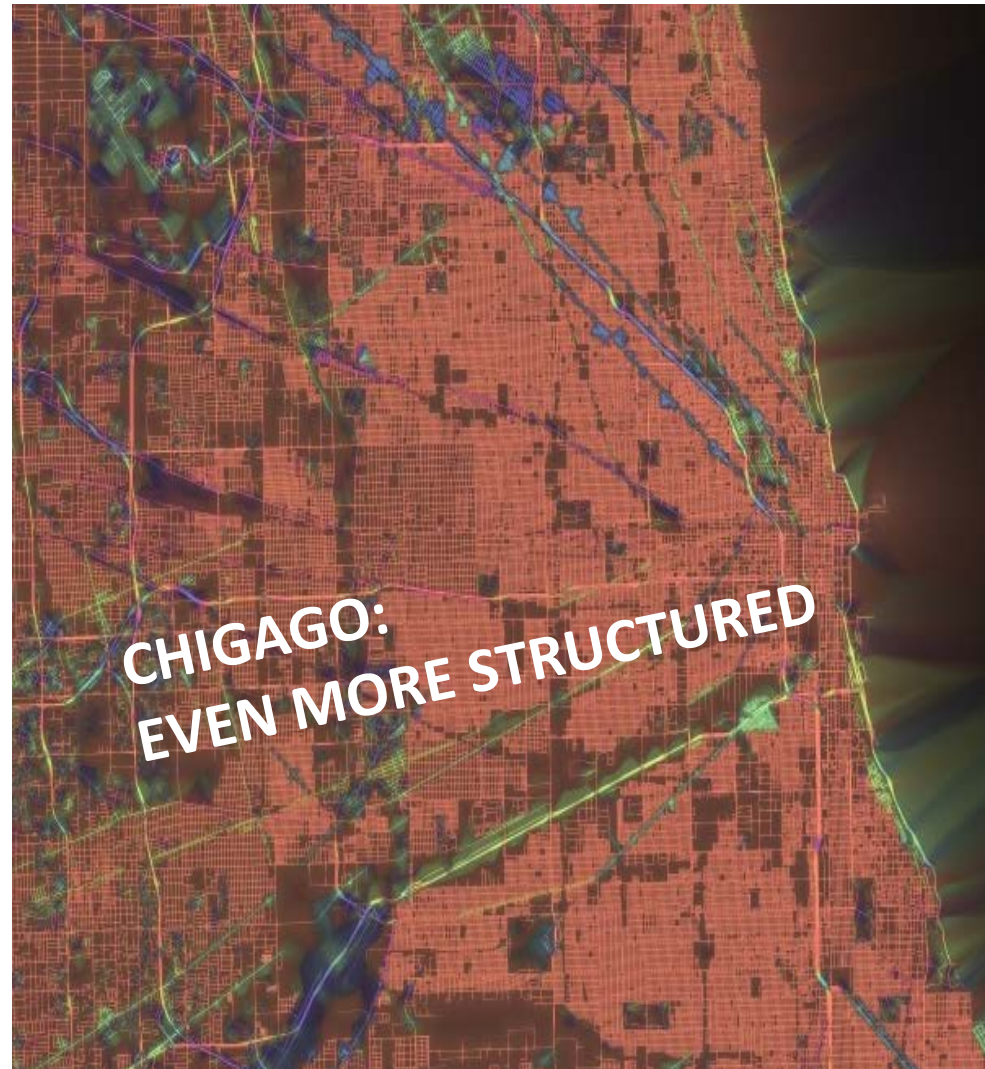


Each city has its character

Street patterns can often be very different

Here are given some representations where color codes street orientation

Extracted from:  
<http://www.datapointed.net/2014/10/maps-of-street-grids-by-orientation/>







That is why  
**Paris is different**  
from so many other cities



# A common test site?

